

IMPORTANCE OF CROSS-SECTIONAL SHAPE FACTOR PARAMETER RESOLUTION IN ACCURATE ASSESSMENT OF TRANSFER LENGTH FOR NON-PRISMATIC RAILROAD CROSSTIES

B. Terry Beck
MNE Department
Kansas State University
Manhattan, KS,USA

Aaron A. Robertson
MNE Department
Kansas State University
Manhattan, KS,USA

Naga Narendra B. Bodapati
CE Department
Kansas State University
Manhattan, KS,USA

Robert J. Peterman
CE Department,
Kansas State University
Manhattan, KS,USA

Chih-Hang John Wu
IMSE Department,
Kansas State University
Manhattan, KS,USA

Kyle A. Riding
CE Department,
Kansas State University
Manhattan, KS,USA

**Presenting Co-Author: B. Terry Beck, Professor
MNE Department, Kansas State University
Manhattan, KS, USA**



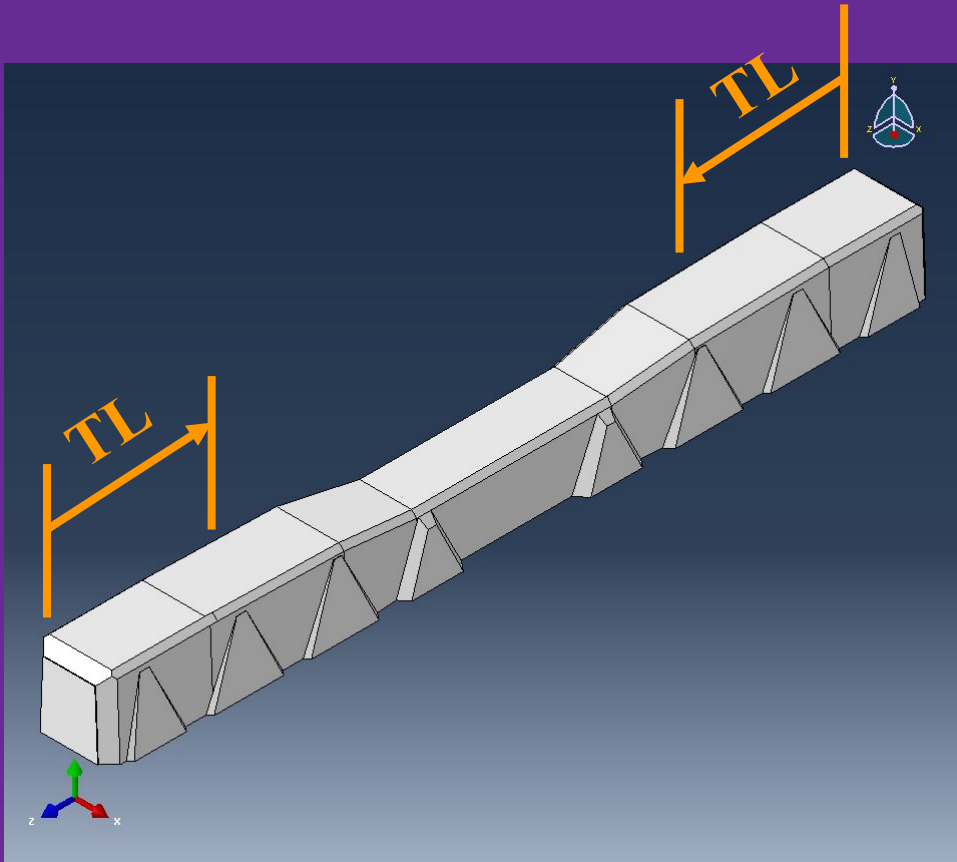
**2016 International Crosstie & Fastening System
Symposium, RailTEC 14-16 June 2016**

Presentation Outline:

- ◆ **Introduction—Importance of Transfer Length**
- ◆ **Transfer Length Measurement from Strain**
- ◆ **Parameters Affecting Transfer Length Assessment**
- ◆ **Objectives—Importance of Shape Factor**
- ◆ **Role of 3D Scanning for Cross-Sectional Parameters**
- ◆ **Effect of Shape Factor Resolution**
- ◆ **Conclusions and Future Work**

Importance of Transfer Length

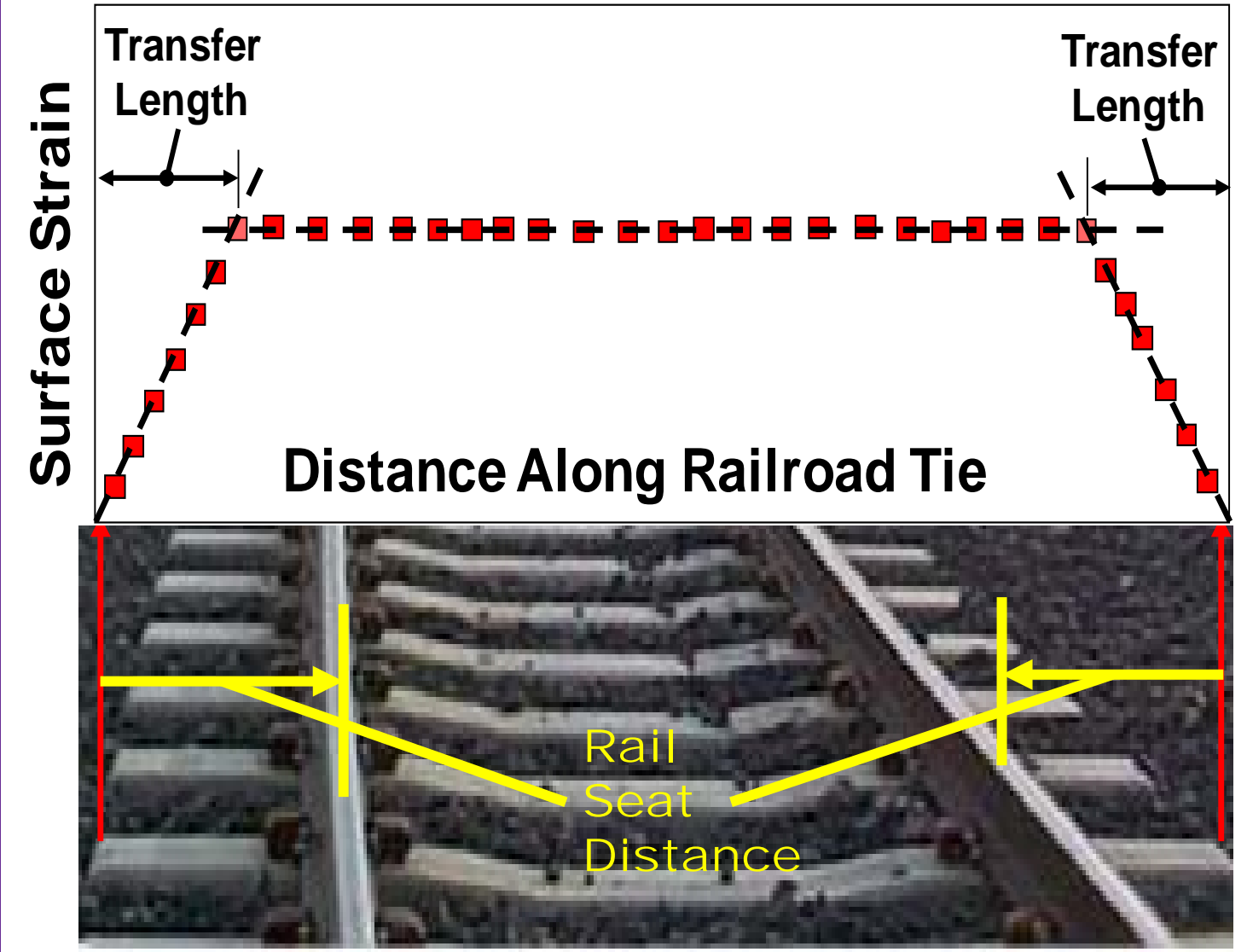
The Transfer Length



The Transfer Length (TL) is the distance required to transfer the entire prestressing force into the concrete cross-tie member



The Transfer Length

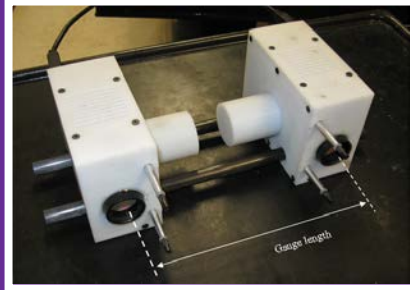
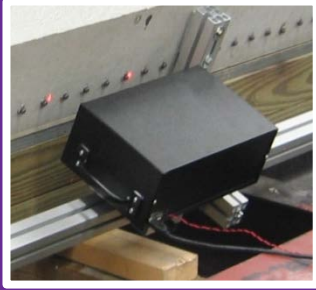


Goal: Avoid In-Track Cross-tie Failure

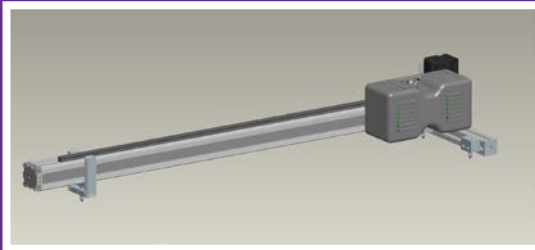


**Transfer Length
Measurement—Role of
Automated Surface Strain
Measurement**

Historical Development of Non-Contact (Optical) Automated Transfer Length Measurement System



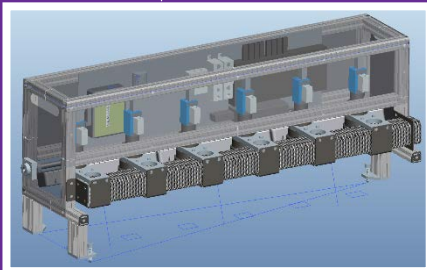
Early Rail-Mounted Manual Prototype
Modular System Design; Patented
Patent No.: US 8,917,384 B2
Date of Patent: Dec. 23, 2014



Automated Dual-Camera System
(Computer-Controlled Traversing)



New Dual Camera
System



Current Prototype 6-Camera System
(Full-Field Strain Capture)

Automated Transfer Length Measurement for In-Plant Quality Control

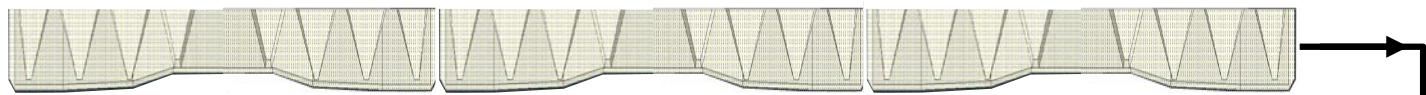
Nominal 6-Camera System

Cutting Operation

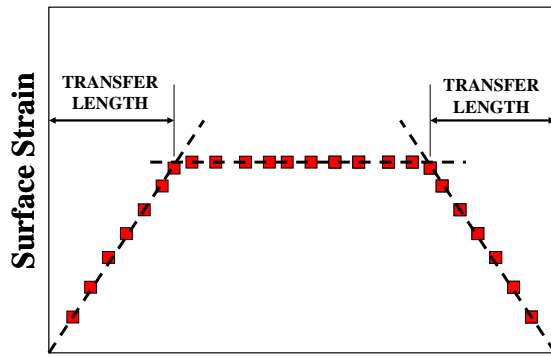
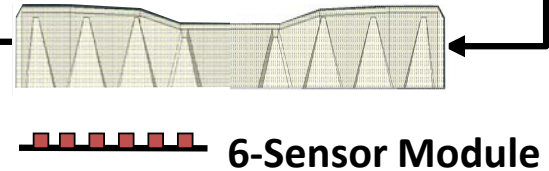
Scan Before De-tensioning

Concrete Tie (Bottom Surface)

6-Sensor Module



Scan After De-tensioning

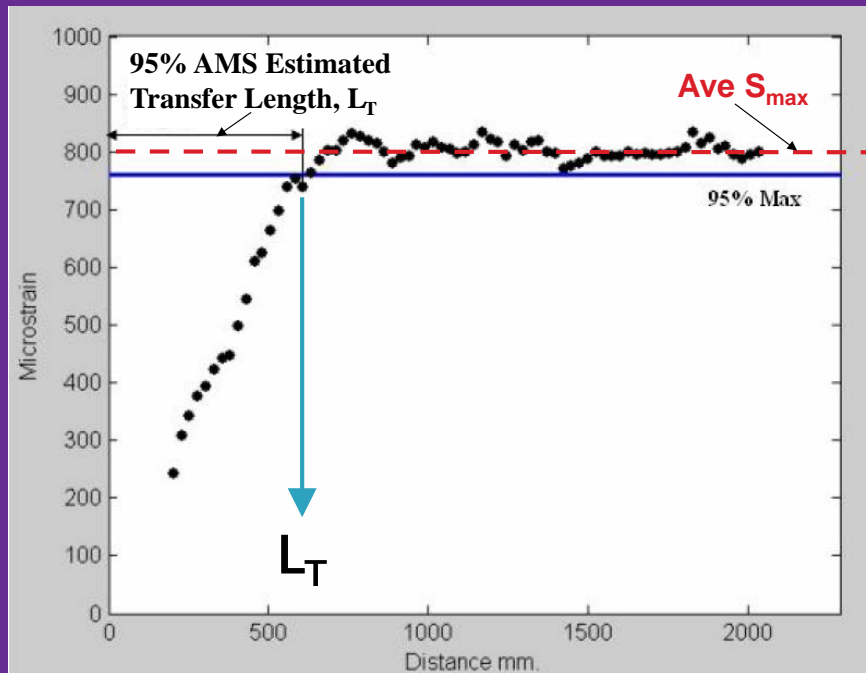


Distance Along Railroad Tie

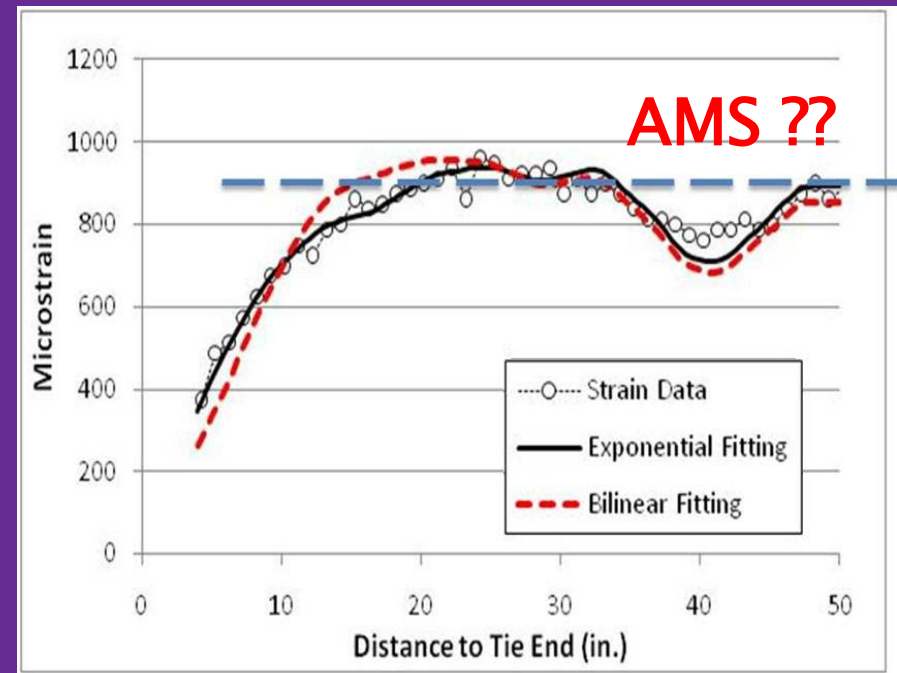
The Zhao–Lee (ZL) Method of Unbiased (Least Squares) Transfer Length Assessment

The Need for Unbiased Transfer Length Algorithm

Prismatic Members

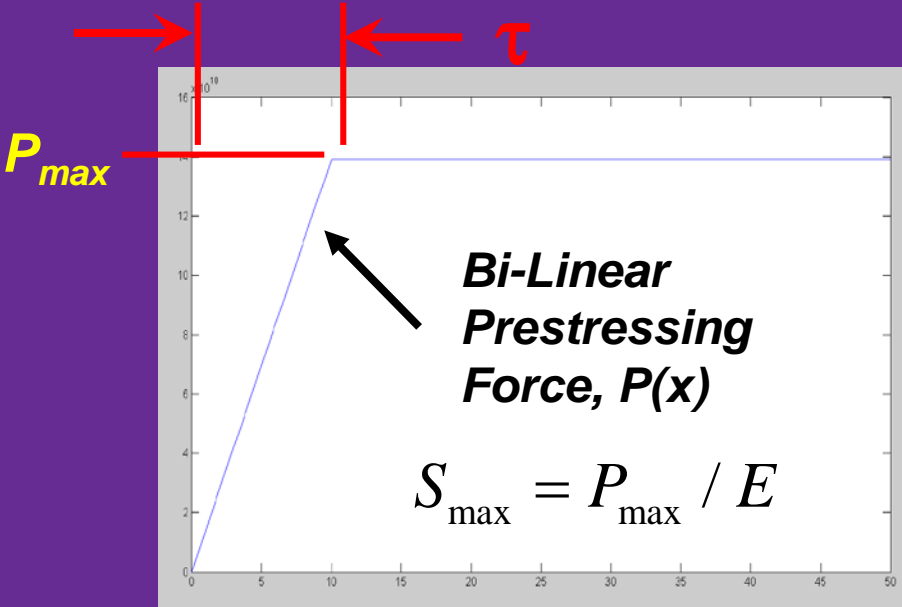


Non-Prismatic Members

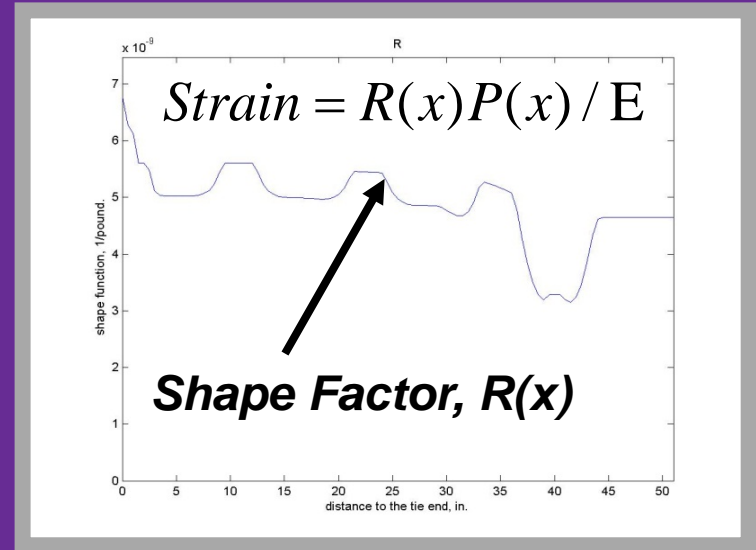


Importance of Accounting for Tie Shape Variation

The Statistical ZL Strain Fitting Algorithm:



+

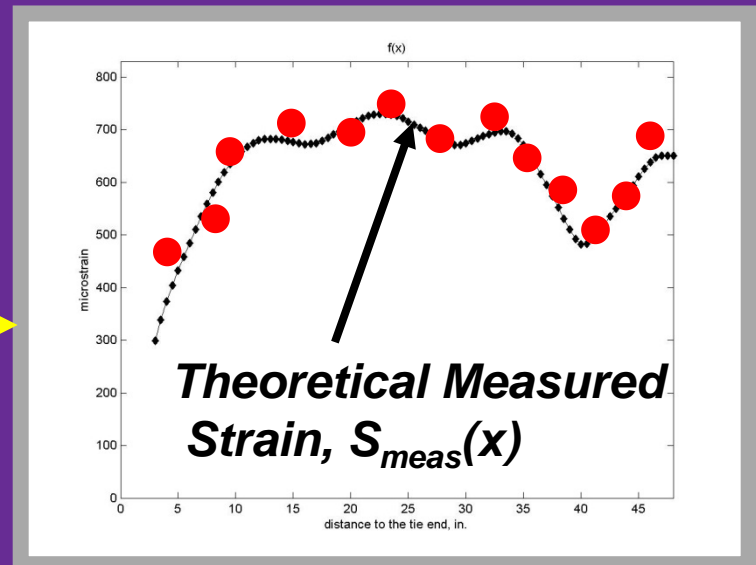


$$S_{\text{meas}}(x, P_{\max}, T_L, TS) =$$

$$\frac{1}{L} \int_{x-\frac{L}{2}}^{x+\frac{L}{2}} [\text{Strain}(x, P_{\max}, T_L) + TS] dx$$

**Averaging over
Finite Gauge Length**

→



Generalized “Zhao-Lee” (ZL) Transfer Length Algorithm:

Find T_L and TS to Minimize MSE:

$$MSE(P_{\max}, T_L, TS) = \frac{\sum_i (S_{meas}(x_i, T_L, TS) - y_i)^2}{N}$$

Where

MSE = Mean Squared Error

y_i = Measured Strain Data

S_{meas} = Theoretical Measured Strain

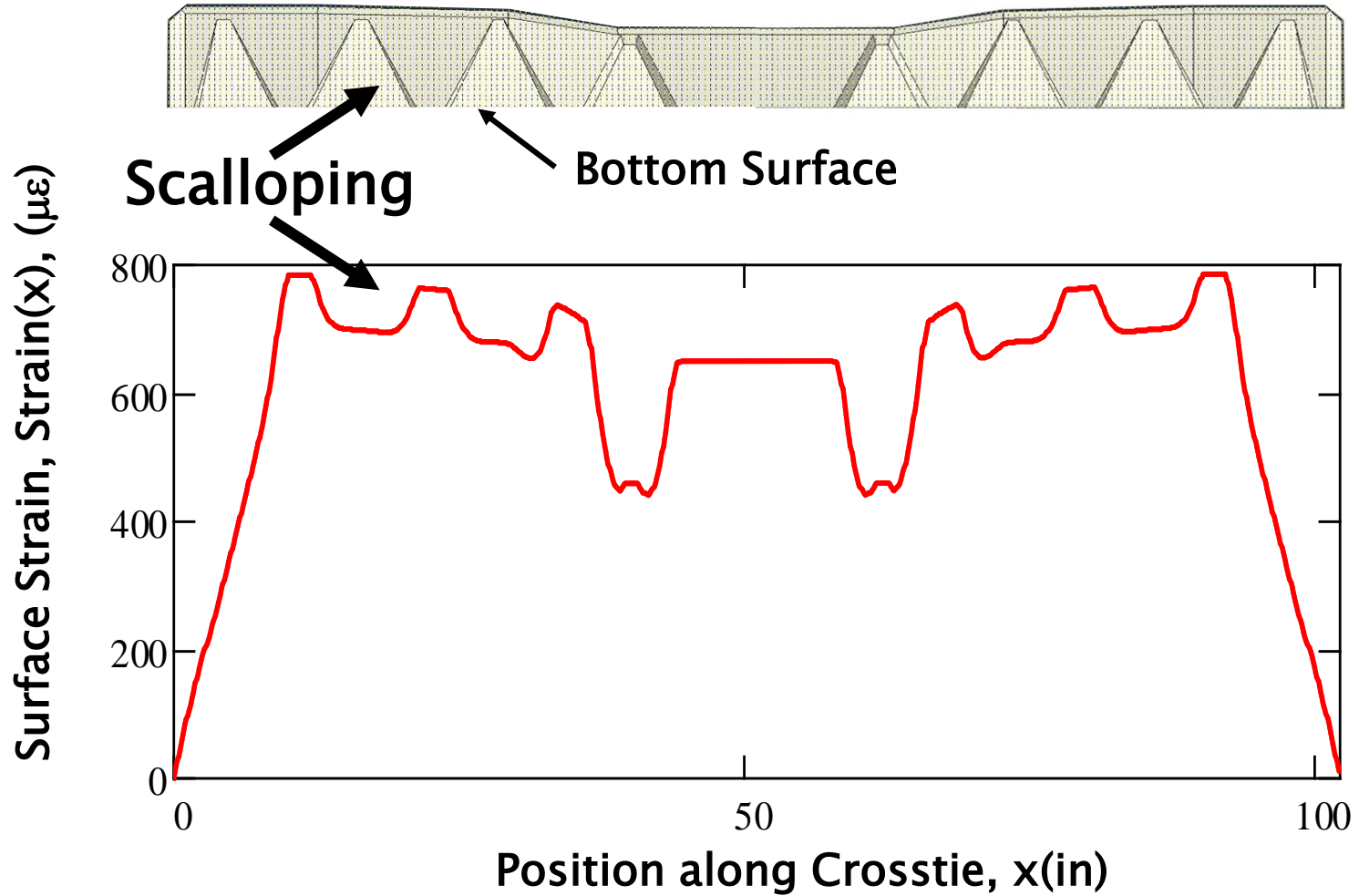
TS = Thermal Strain Offset

**Parameters Affecting Transfer
Length Measurement
from Longitudinal Surface Strain**

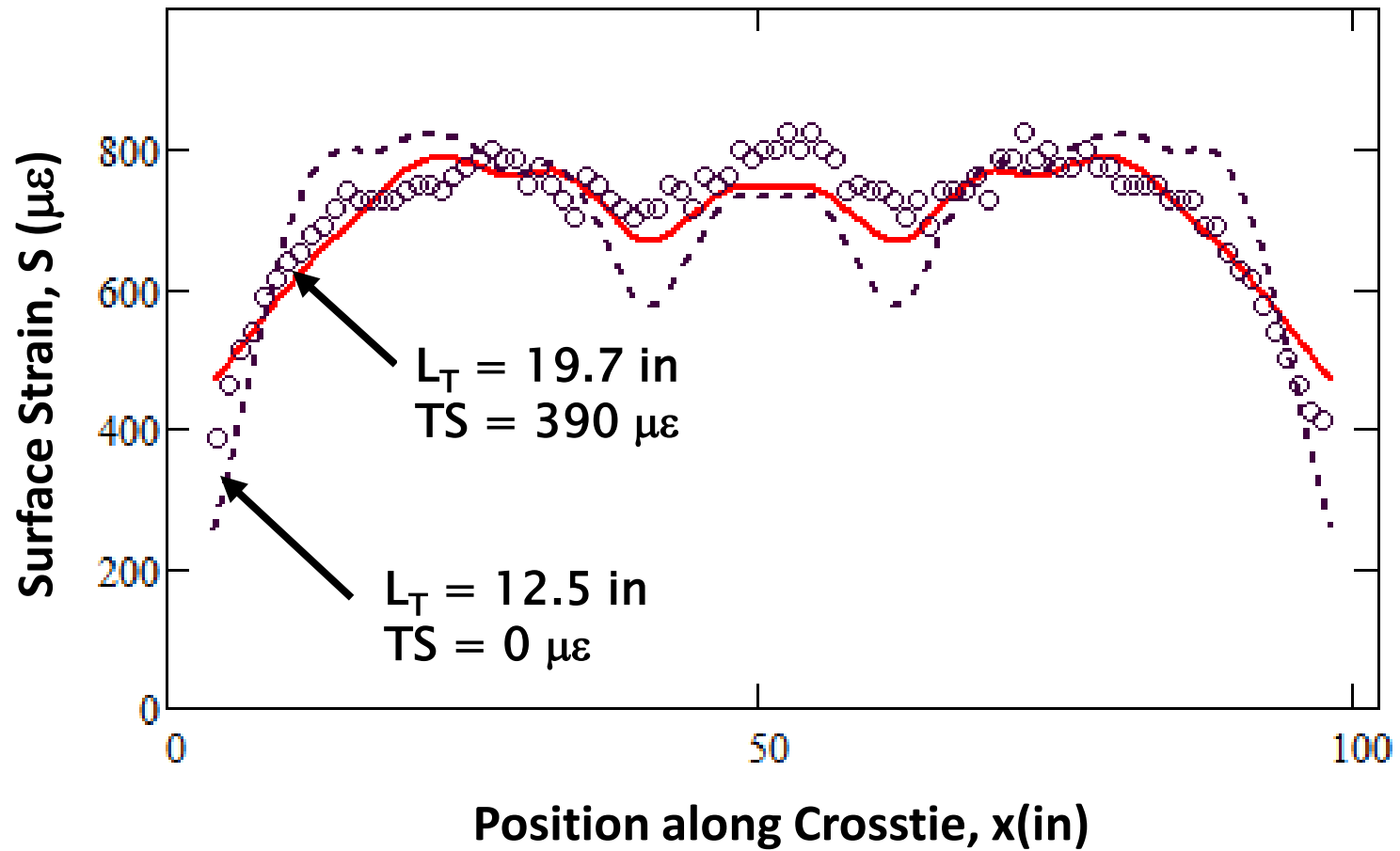
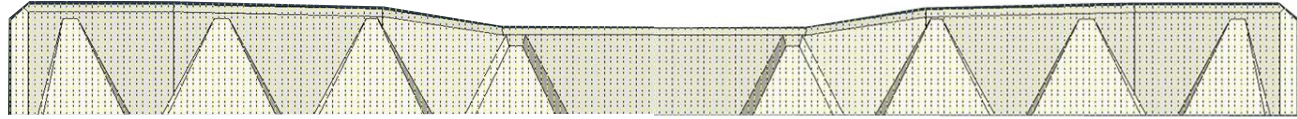
Parameters that Affect Transfer Length Measurement

- ◆ Surface Strain Measurement Accuracy
- ◆ Strain Measurement Span and Sampling Interval
- ◆ Strain Instrument Gauge Length
- ◆ Assumed Shape of Prestressing Force Distribution
- ◆ Effect of Thermal (Offset) Strain
- ◆ Extraction Algorithm (95% AMS or Zhao-Lee)
- ◆ Cross-Section Shape (Shape Factor Variation)

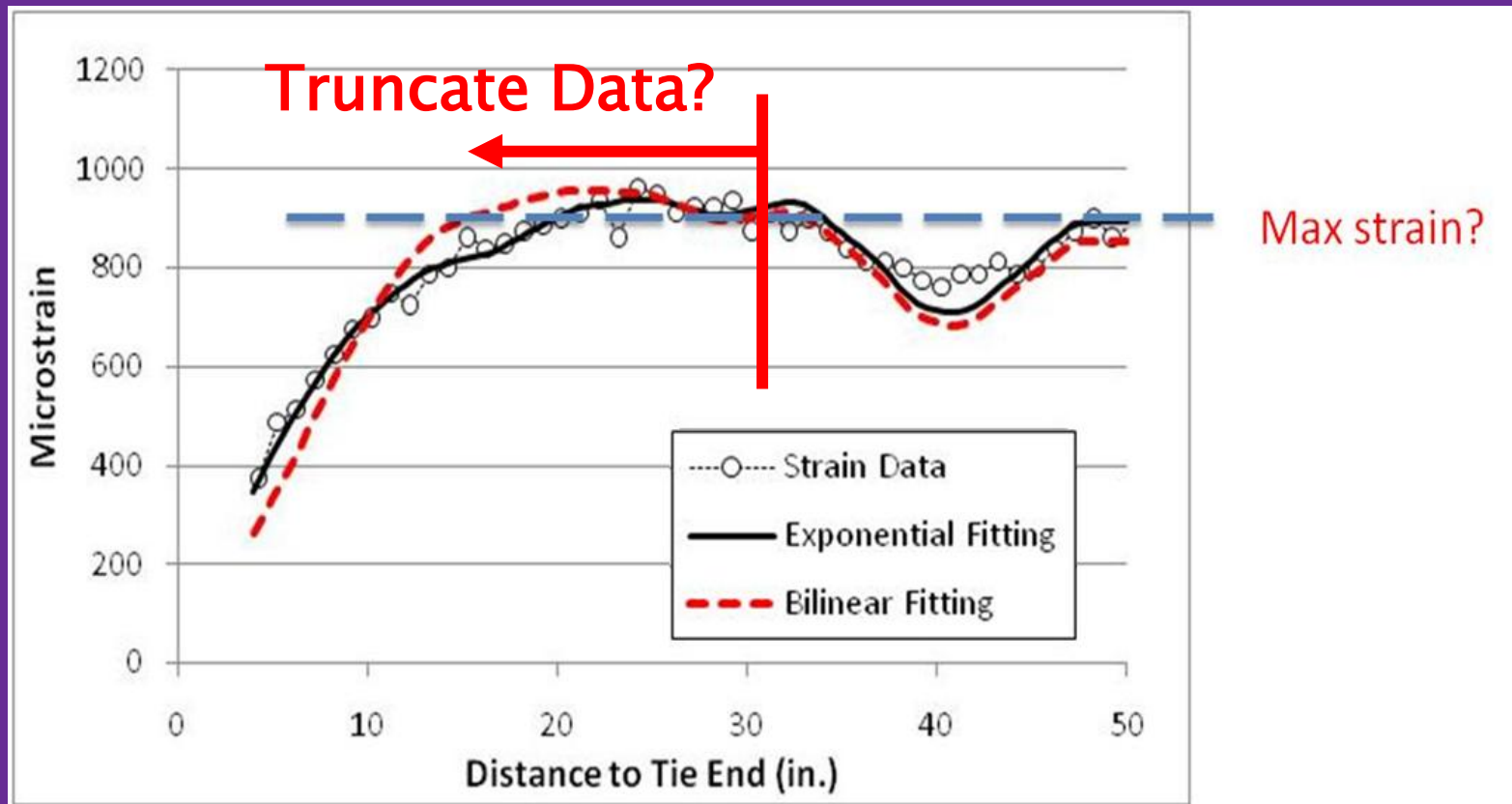
Complex Crosstie Strain Distribution



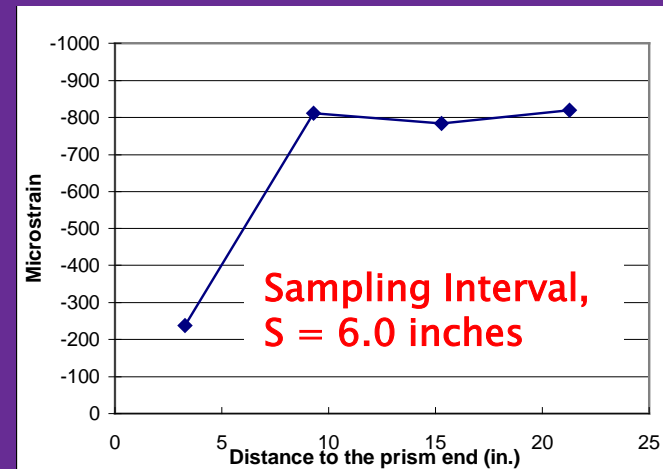
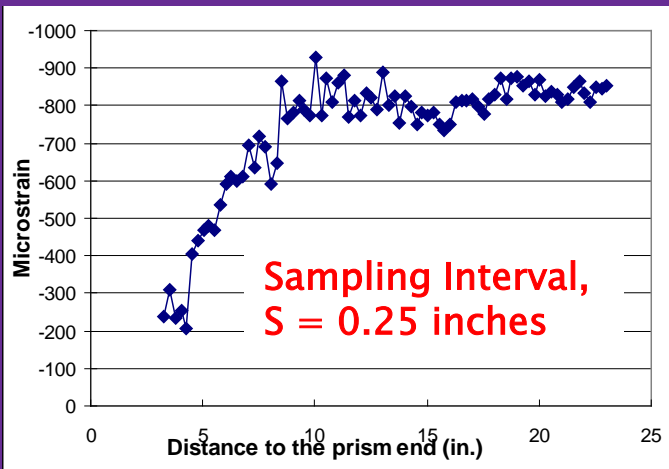
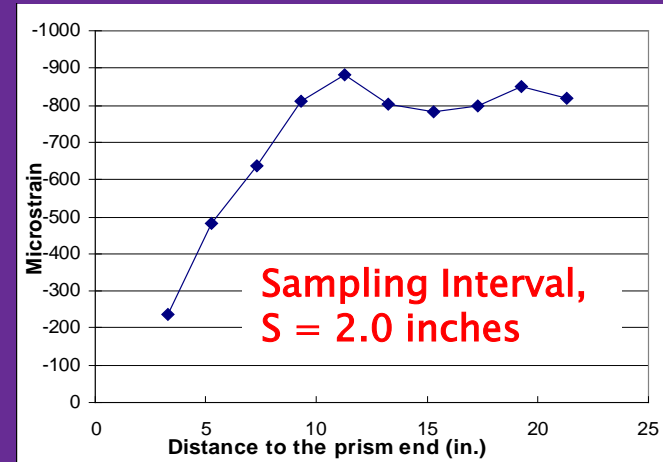
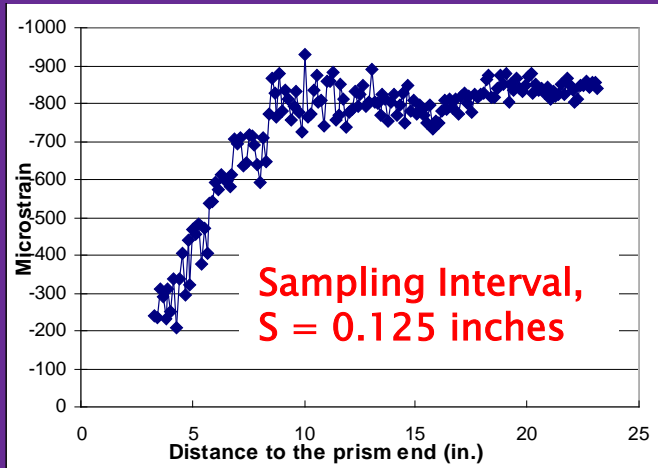
Effect of Thermal (Offset) Strain



What is the Average Maximum Strain (AMS)?




Automated Strain Measurements at Various Strain Sampling Intervals, S



Independence of Transfer Length Assessment (ZL Method) at Various Sampling Intervals

| Sampling Interval (in.) | Estimated Transfer Length (in.) |
|-------------------------|---------------------------------|
| 0.125 | 9.1 |
| 0.25 | 9.0 |
| 0.5 | 9.2 |
| 1 | 9.5 |
| 2 | 9.0 |
| 4 | 9.6 |
| 6 | 9.0 |
| 8 | 10.3 |

6-Camera System



The diagram shows a 6-camera system, which is a long, narrow rectangular frame containing six camera modules. The system is mounted on a base. A red arrow points from the '6' sampling interval row in the table to the diagram, and another red arrow points from the '6' sampling interval row to the '9.0' estimated transfer length value.

The Role of 3D Optical Scanning in Current Research Efforts

In-Service Crossties at Pueblo Colorado Facility (TTCI)—Major Source of Ties



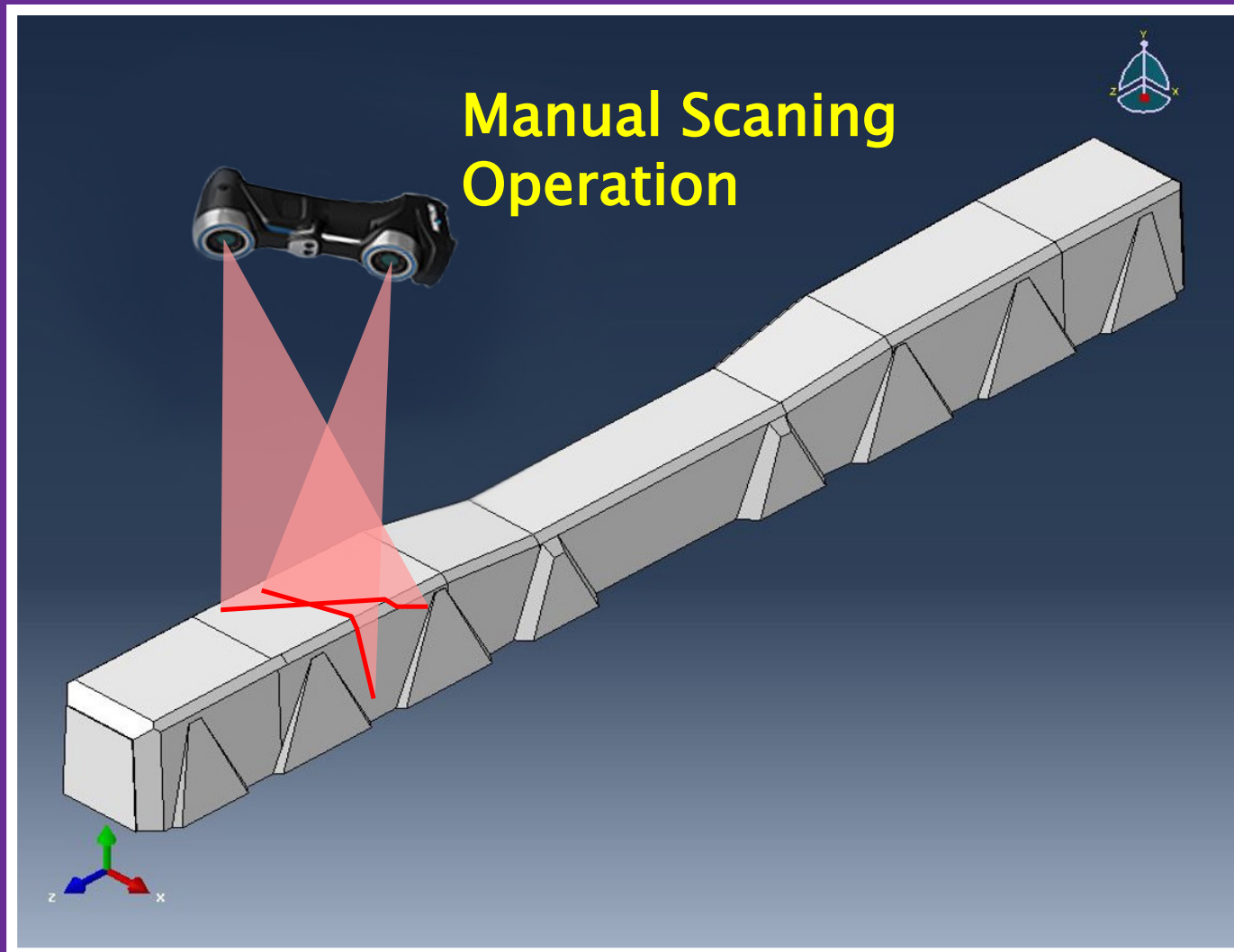
CXT Crossties from In-Track TTCI Facility



KEY Role of 3D Scanning:

- ◆ Quantify Surface Geometry of Previously Manufactured Ties that have been in Service
- ◆ Produce Accurate 3D Solid Body Models of In-Service Ties for Later Analysis
- ◆ Direct Comparison of Overlapping Images of 3D Scanned Ties
- ◆ Quantify the Amount of Abrasion Which Has Occurred During the Life of In-Service Ties

Schematic of 3D Optical Scanning of Railroad Crosstie Using Commercial Device



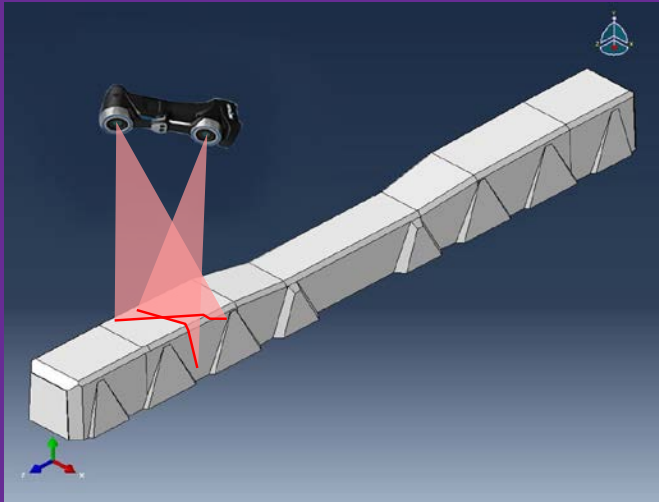
Commercial 3D Scanner Specifications:



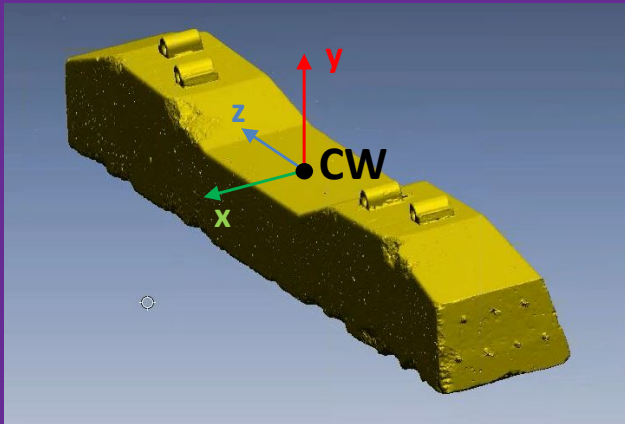
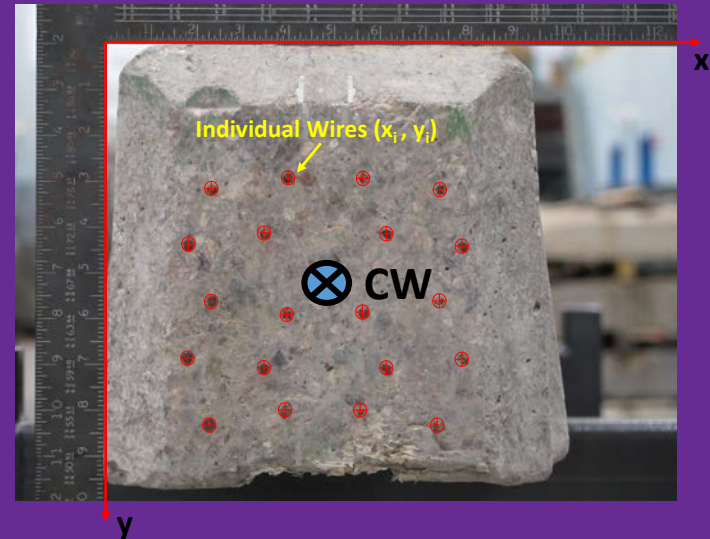
- ◆ 7 Pair Intersecting Laser Light Sheets
- ◆ Local Scanning Area: 275 x 250 mm (10.8 x 10 in.)
- ◆ Resolution: 0.050 mm (0.002 in.)
- ◆ Accuracy: 0.030 mm (0.0012 in.)
- ◆ Volumetric Accuracy: 0.020 mm + 0.060 mm/m
(0.0008 in. + 0.0007 in./ft)
- ◆ Depth of Field: 250 mm (10 in.)

Slicing of Solid Model & Parameter Analysis

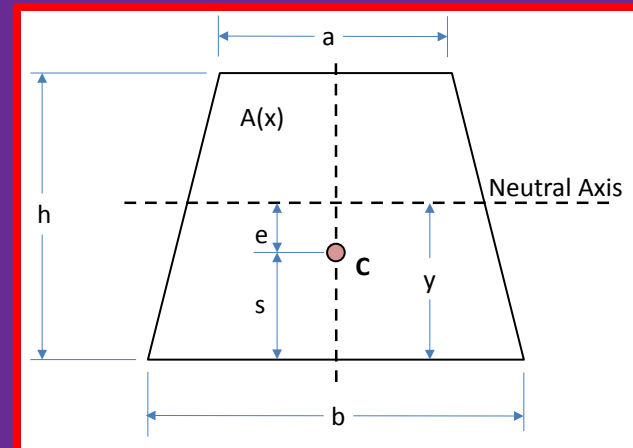
3D to Point Cloud Model of Tie



Photograph Crosstie End Wire Configuration
(Establish Wire centroid Position, CW)



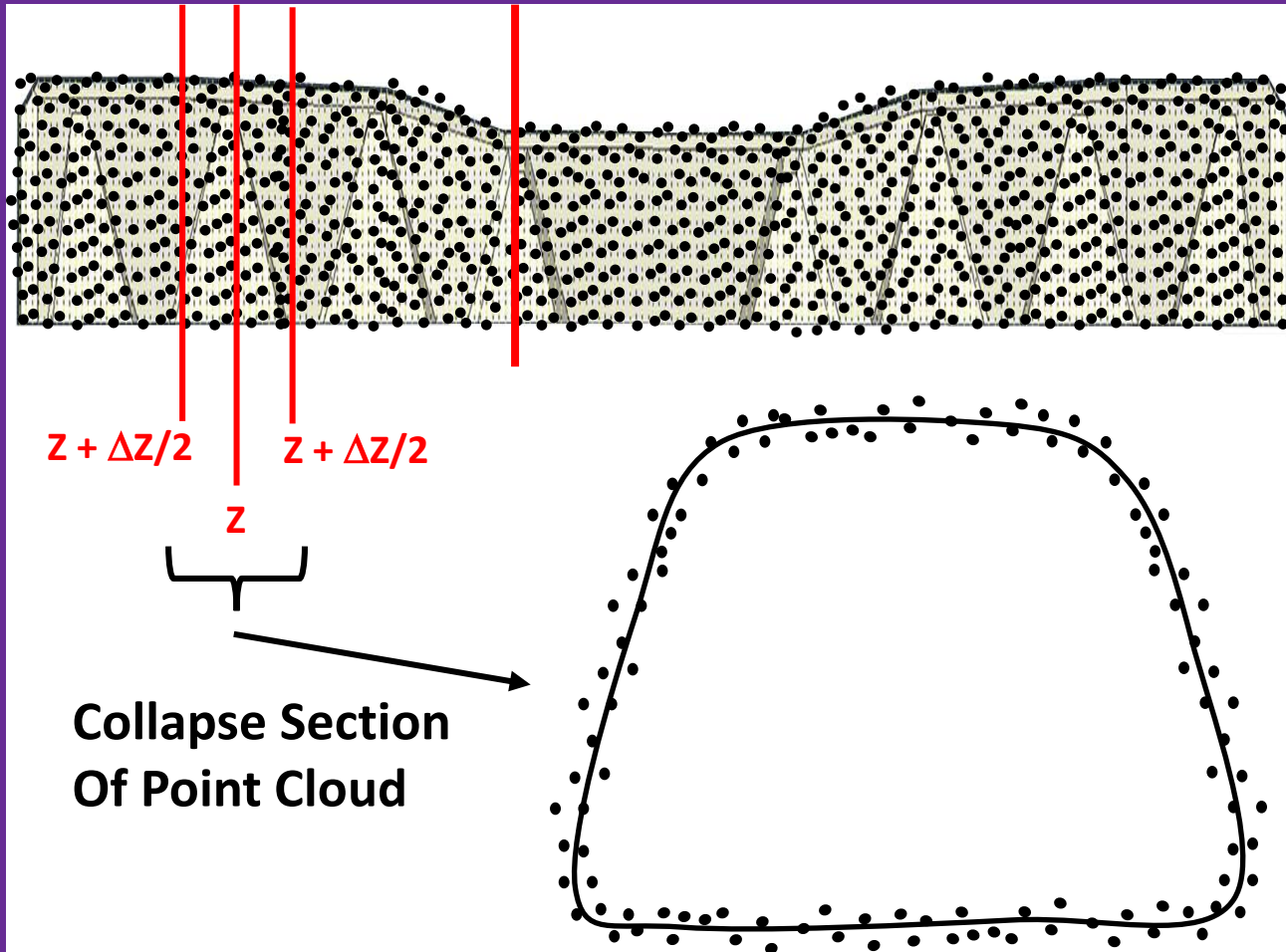
Establish x,y,z
Coordinate System



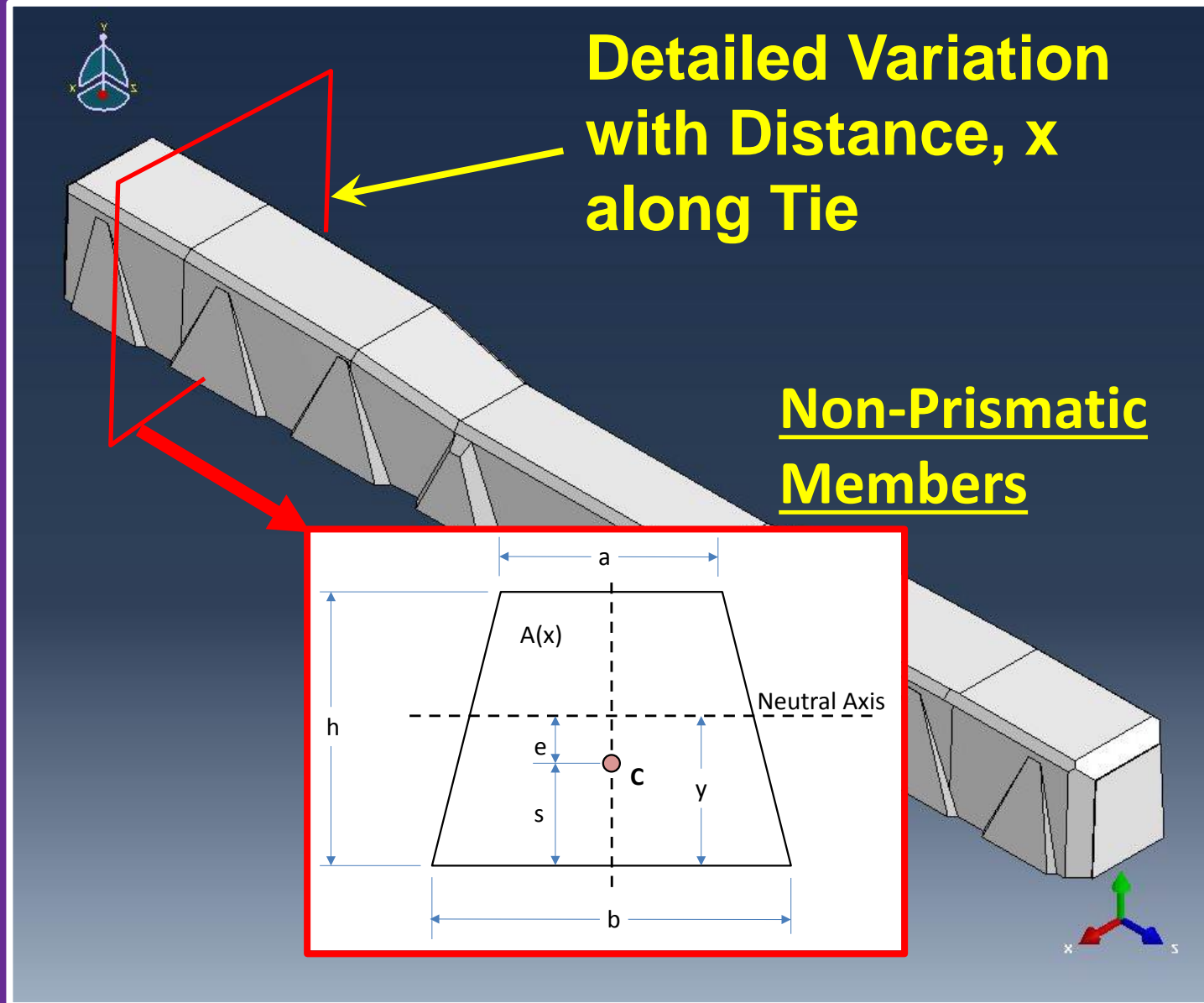
Extract Cross-section
Parameters

Extracting Slices from Crosstie Point Cloud

$\leftarrow \Delta x \rightarrow$ $\Delta x = \text{Resolution}$



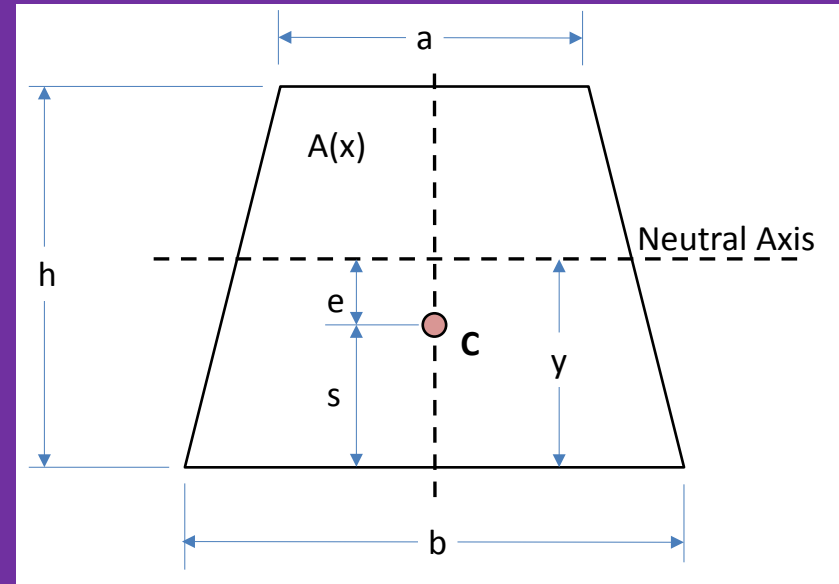
Extraction of Tie Parameters From CAD or Scan



Shape Factor, $R(x)$, for Crosstie

$$\text{Strain}(x) = \frac{P(x)R(x)}{E}$$

$$R(x) = \frac{1}{A(x)} + \frac{e(x)y(x)}{I(x)}$$



where

$P(x)$ = Prestressing force

$A(x)$ = Cross-sectional area

$e(x)$ = Eccentricity

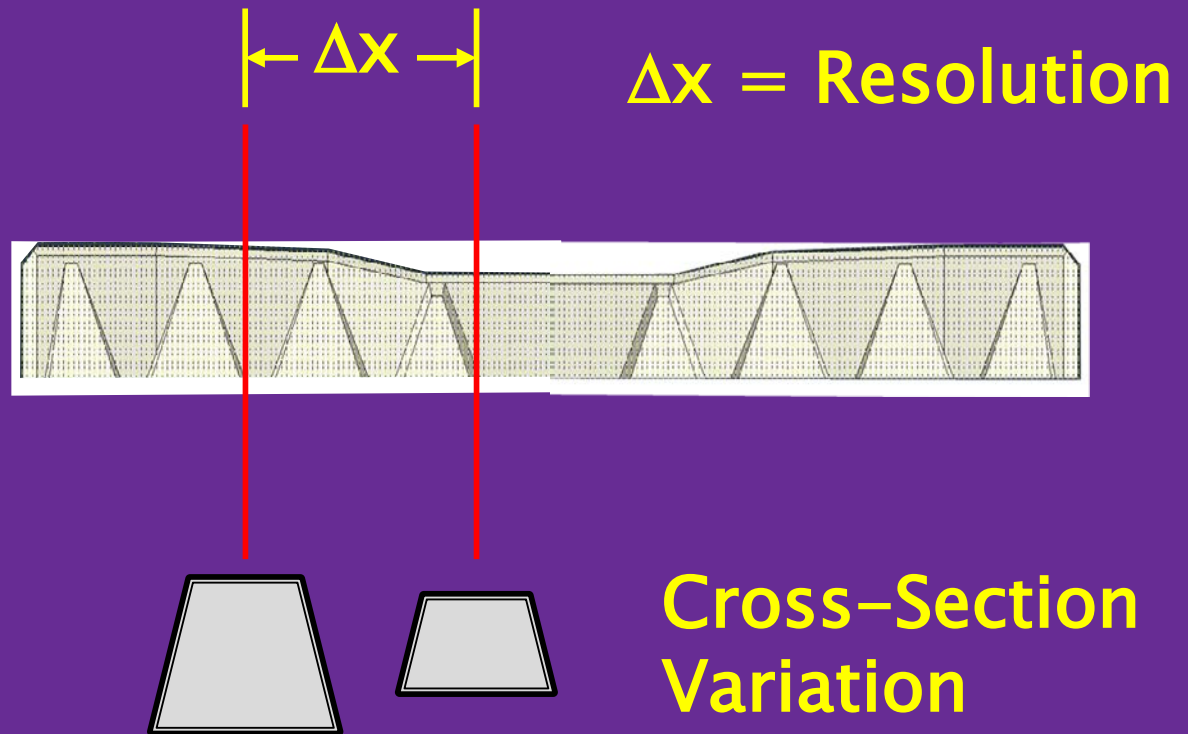
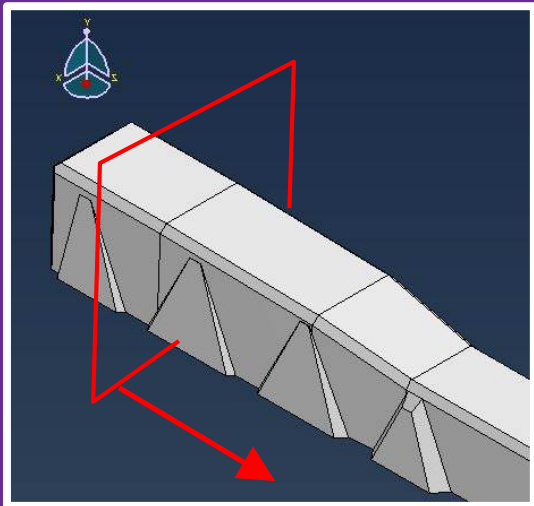
$y(x)$ = Distance to neutral axis

$I(x)$ = Area Moment of Inertia

E = Young's Modulus

Effect of Shape Factor Resolution
on Crosstie Shape Parameters
And Transfer Length

Question: How Does Shape Factor Resolution Affect Transfer Length Assessment?



Photographs of Typical CXT Ties



(a) Left tie end



(b) Right tie end



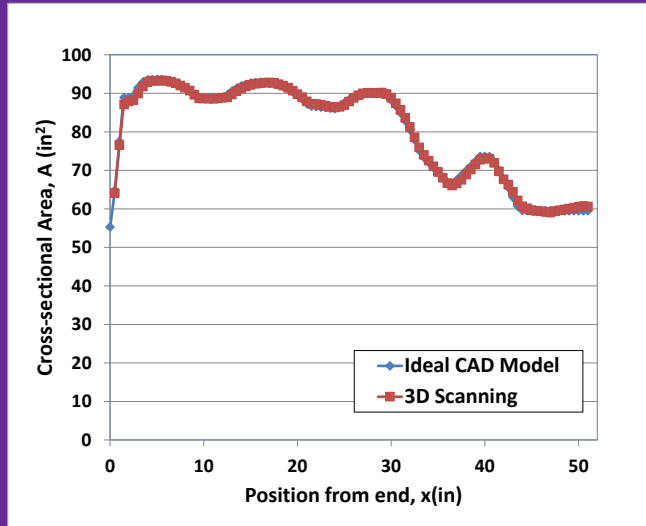
(c) Enlarged left end



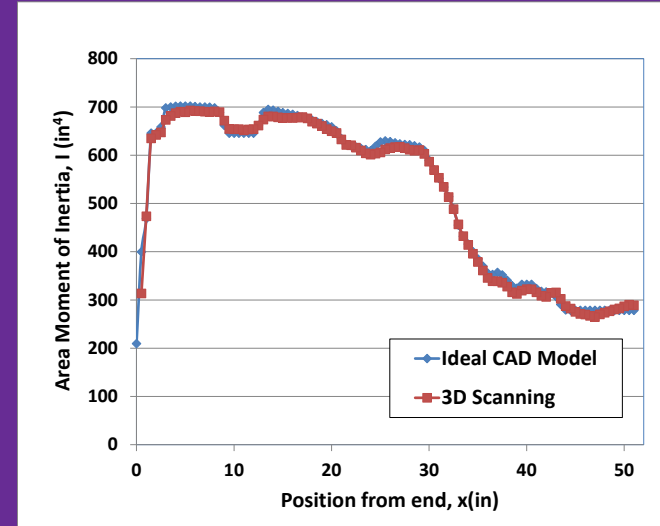
(d) Enlarged right end

Extracted CXT Crosstie Cross-Section Parameters

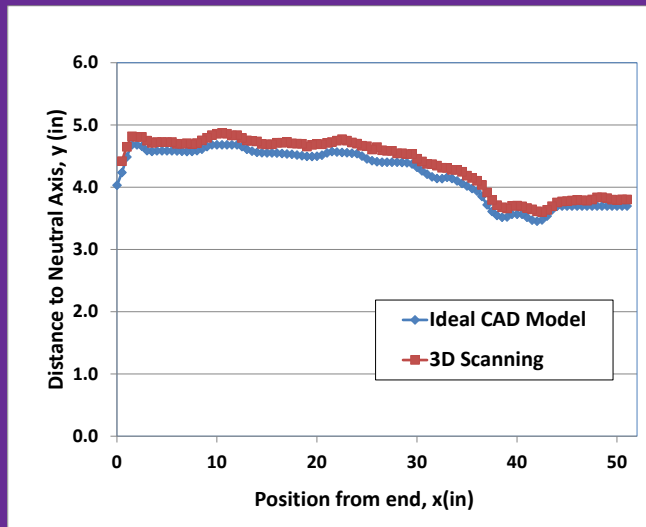
Cross Sectional Area, A



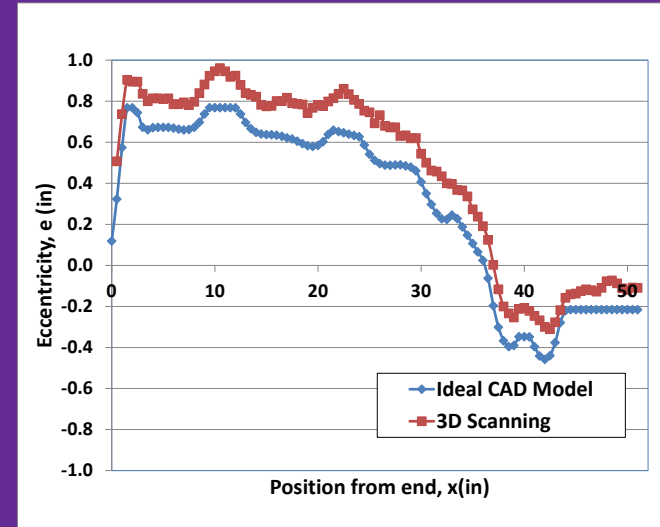
Area Moment of Inertia, I



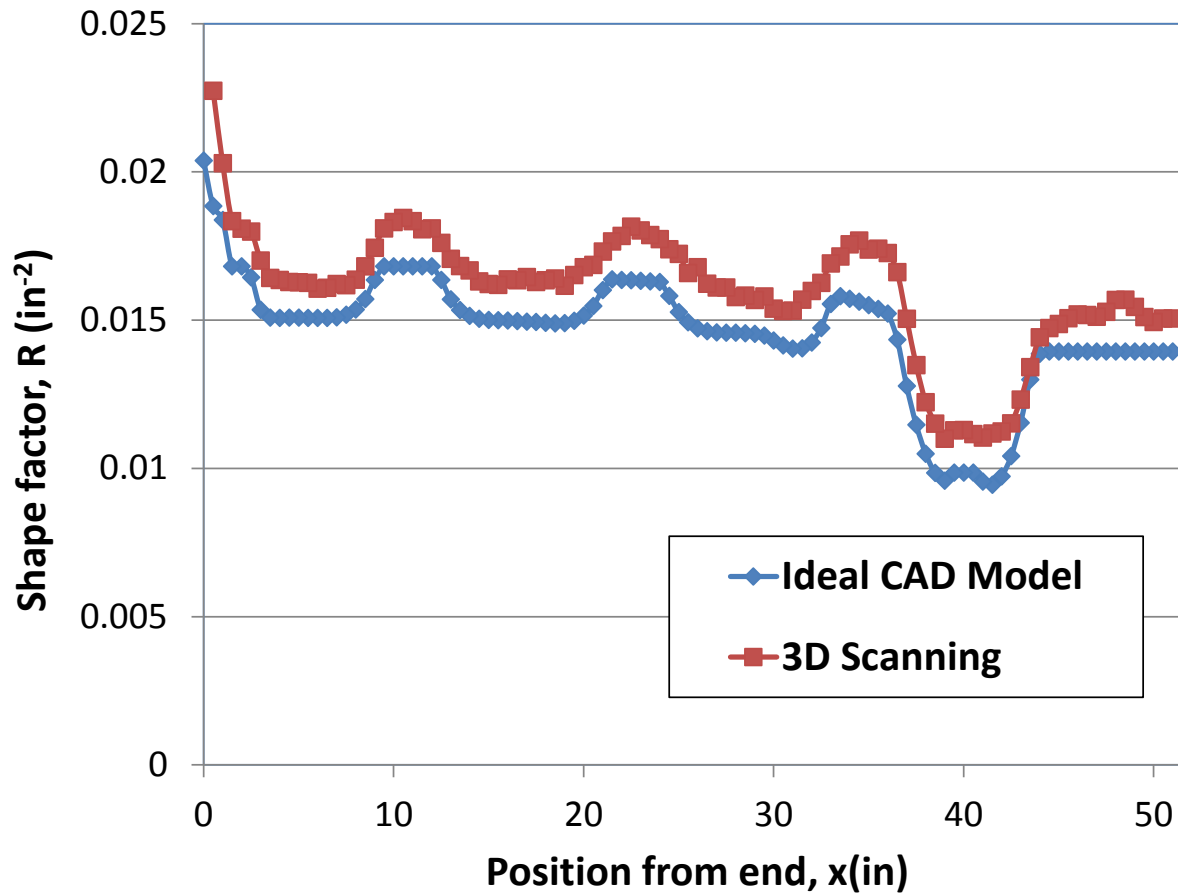
Neutral Axis Position, y



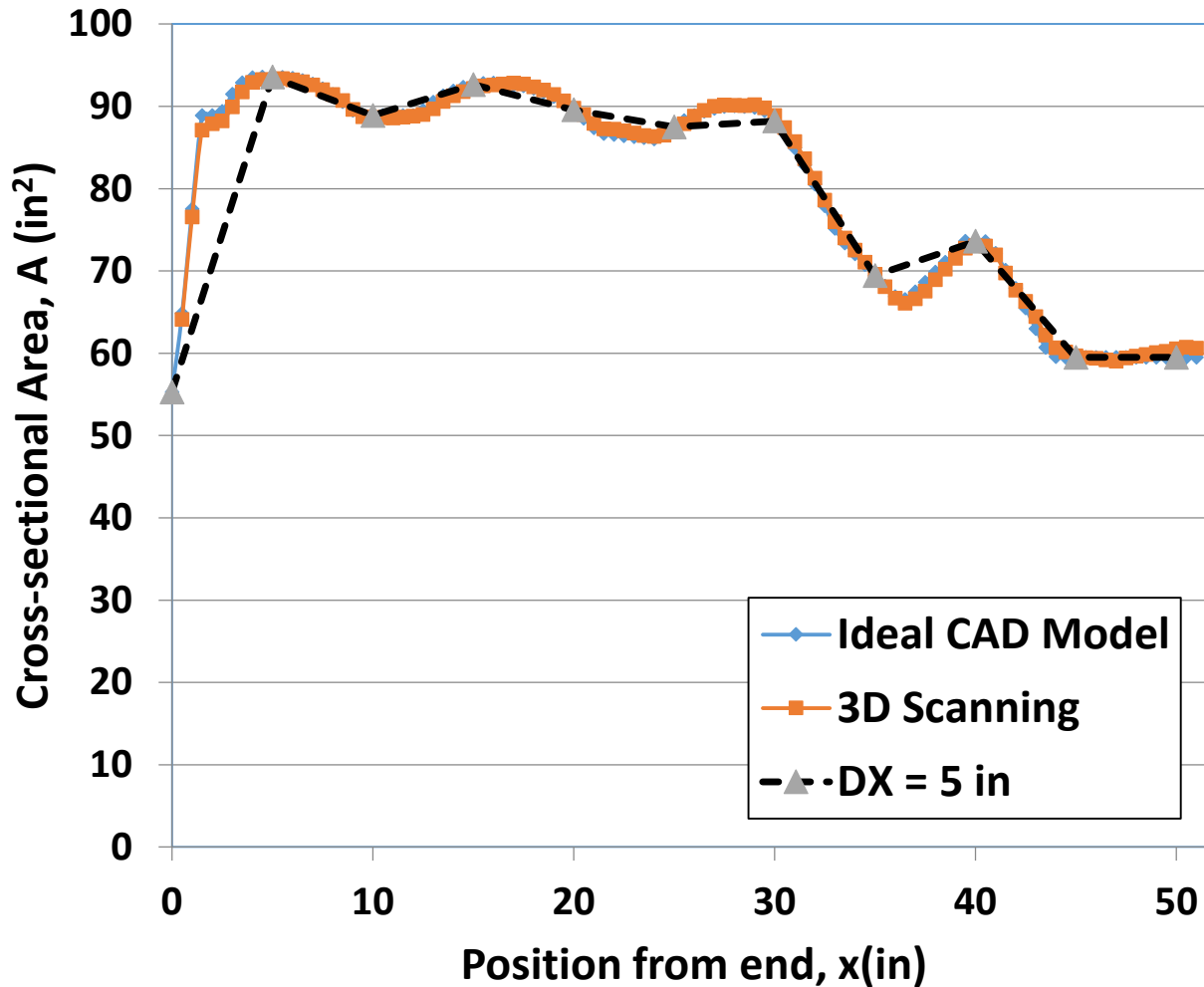
Eccentricity, e



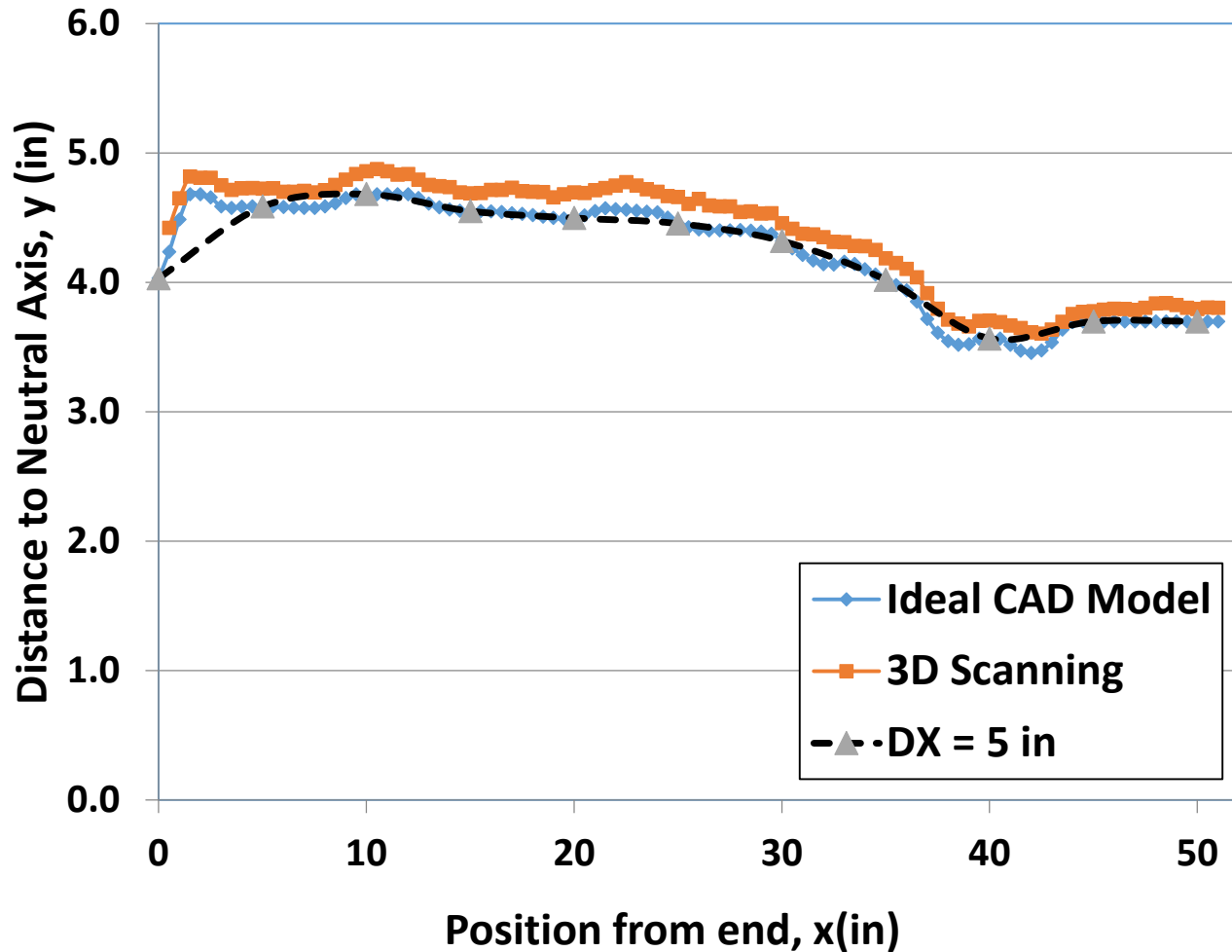
CXT Crosstie Shape Factor



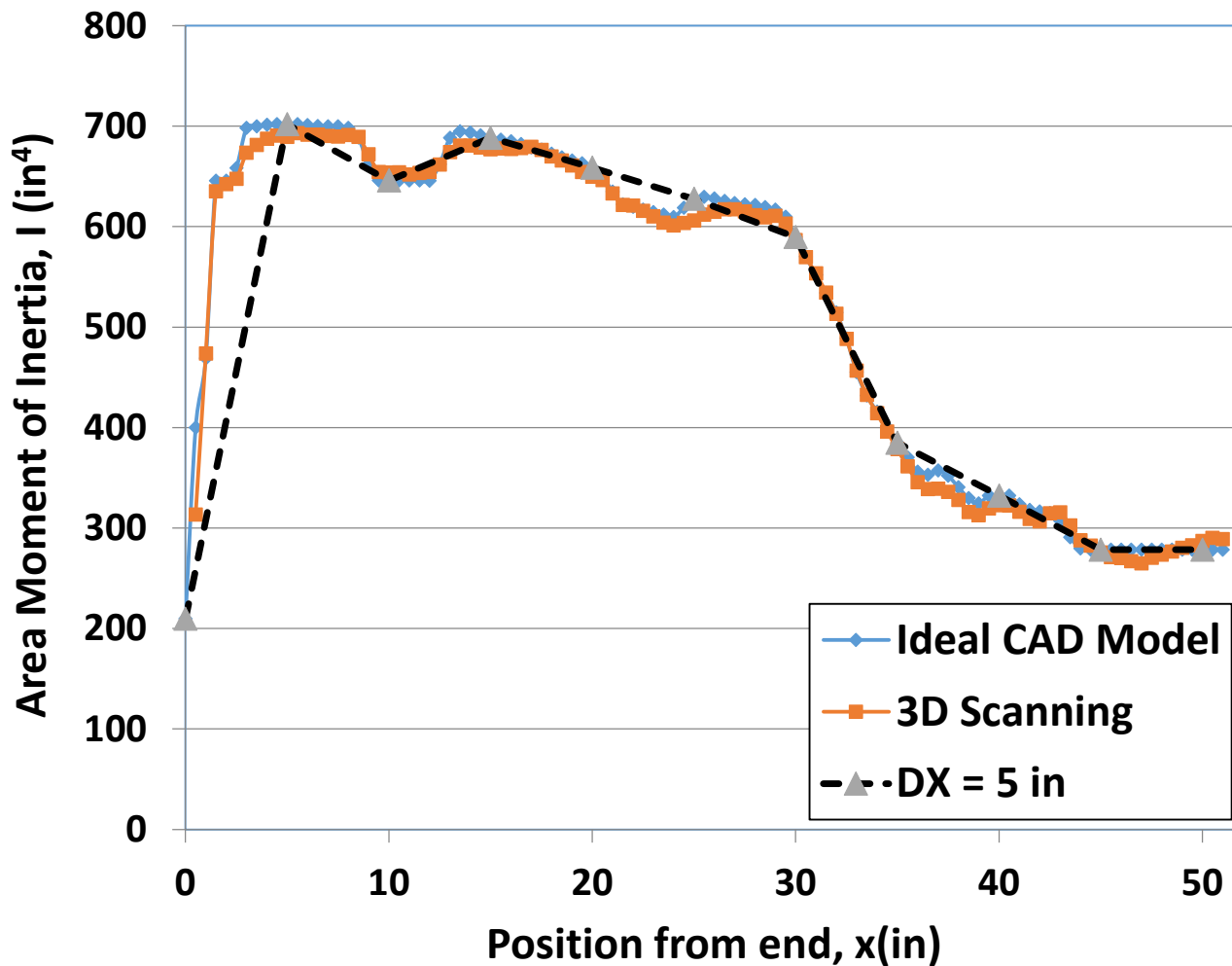
Reduced Resolution Crosstie Area, A



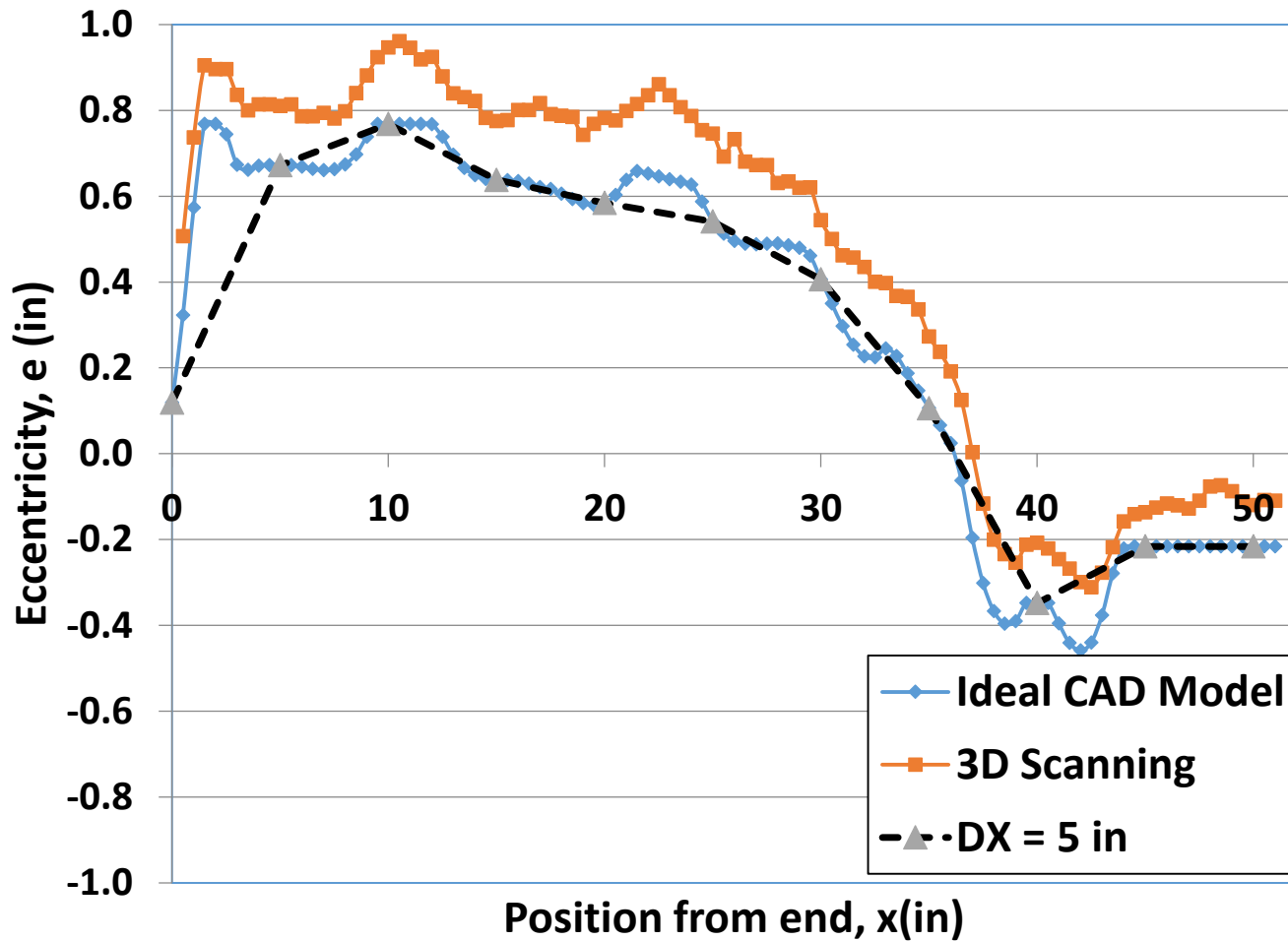
Reduced Resolution Area Centroid, y



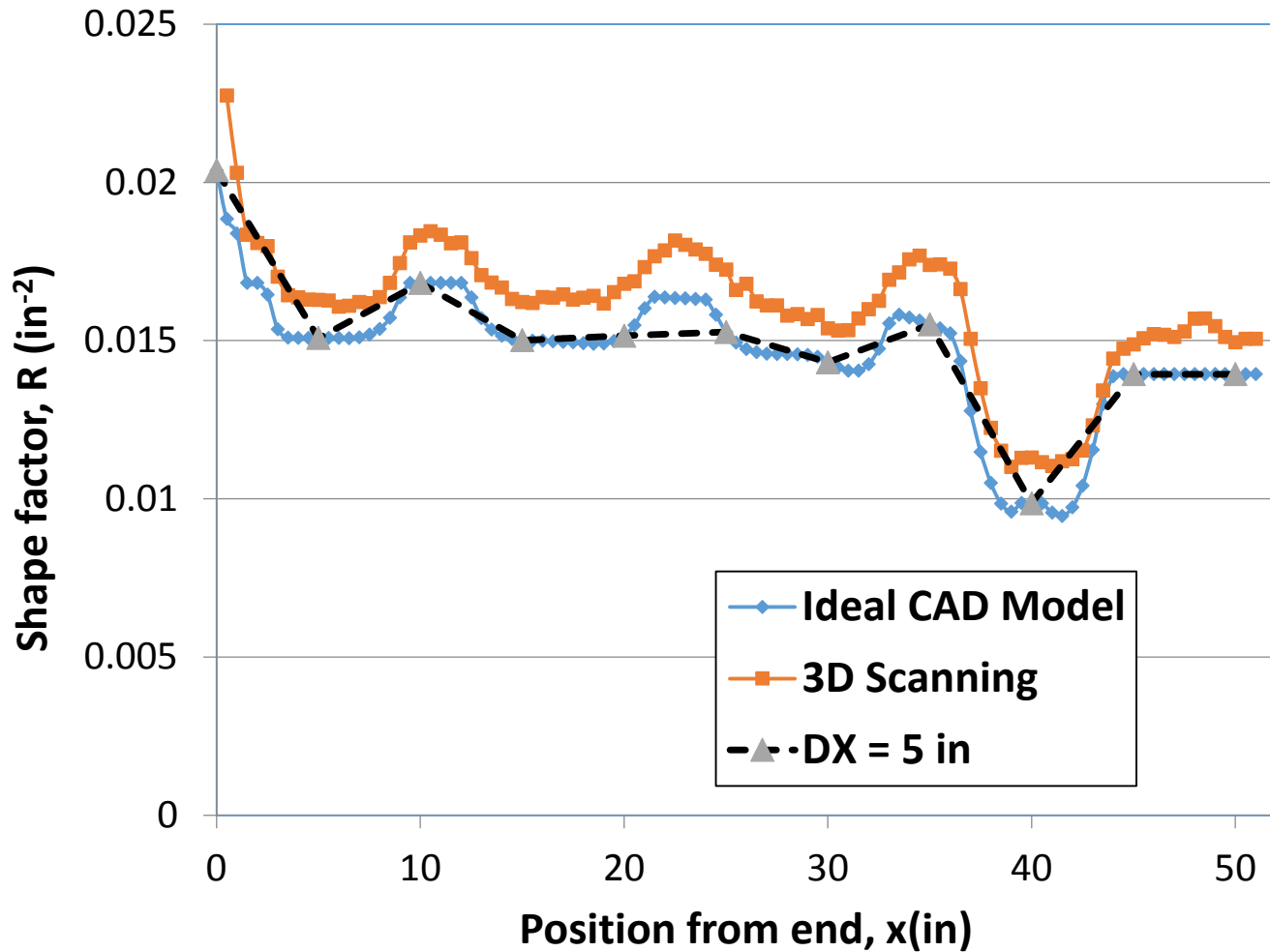
Reduced Resolution Crosstie Area Moment, I



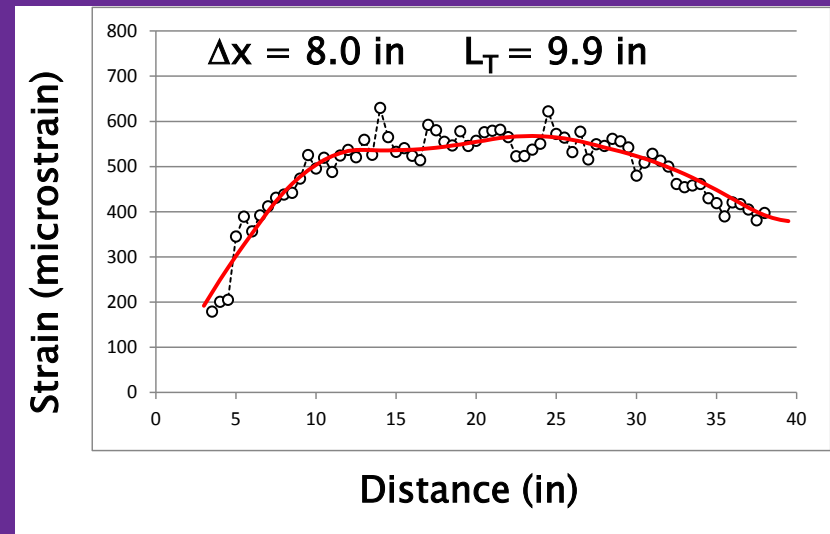
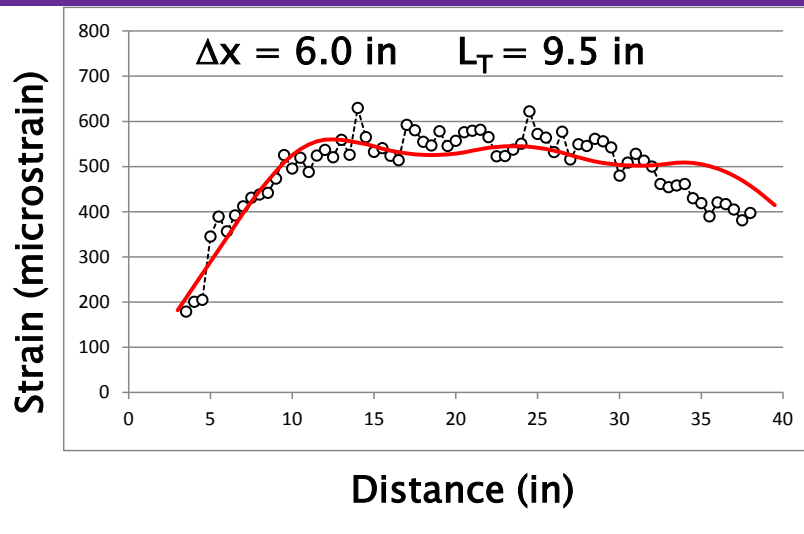
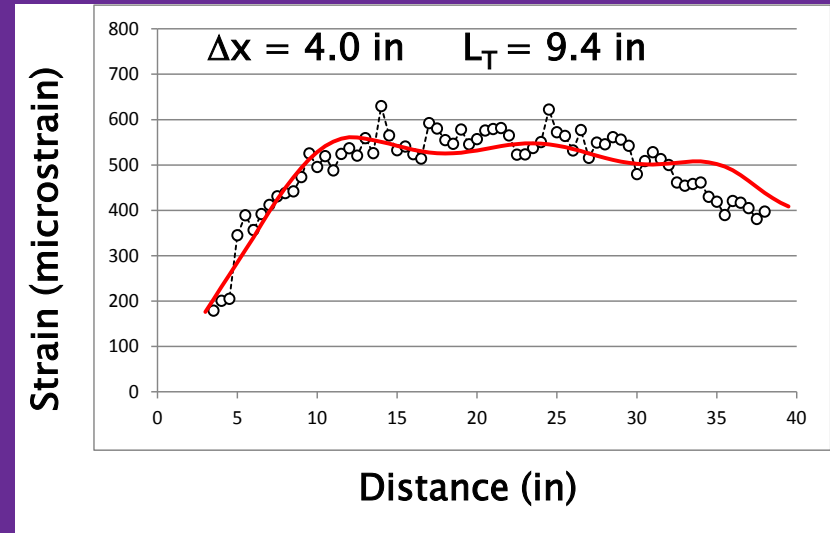
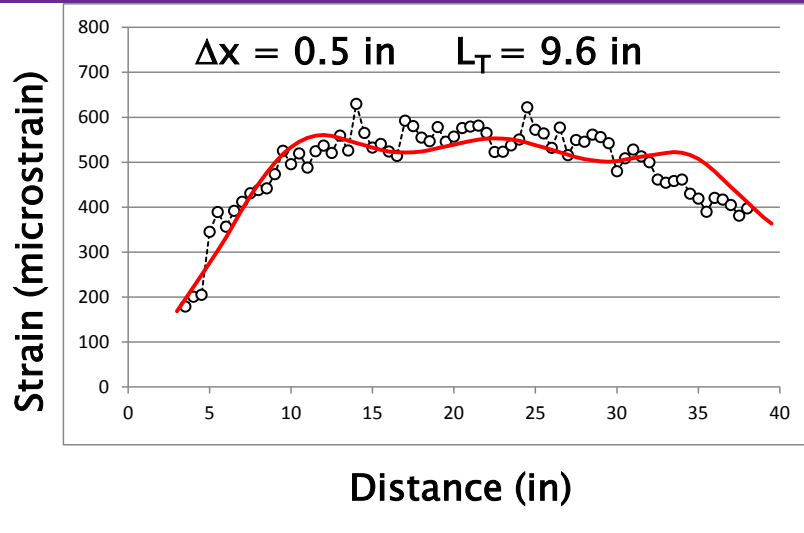
Reduced Resolution Crosstie Eccentricity, e



Reduced Resolution Crosstie Shape Factor, R



Effect of Resolution on Strain Profile



Transfer Length Assessment—Effect of Reduced Slicing Resolution (CXT Tie Results)

CAD (Simulated)

| Δx (in) | L_T (in) |
|-----------------|------------|
| 0.5 | 10.0 |
| 1.0 | 10.0 |
| 2.0 | 10.0 |
| 4.0 | 9.9 |
| 5.0 | 10.4 |
| 6.0 | 10.0 |
| 7.0 | 9.8 |
| 8.0 | 10.2 |

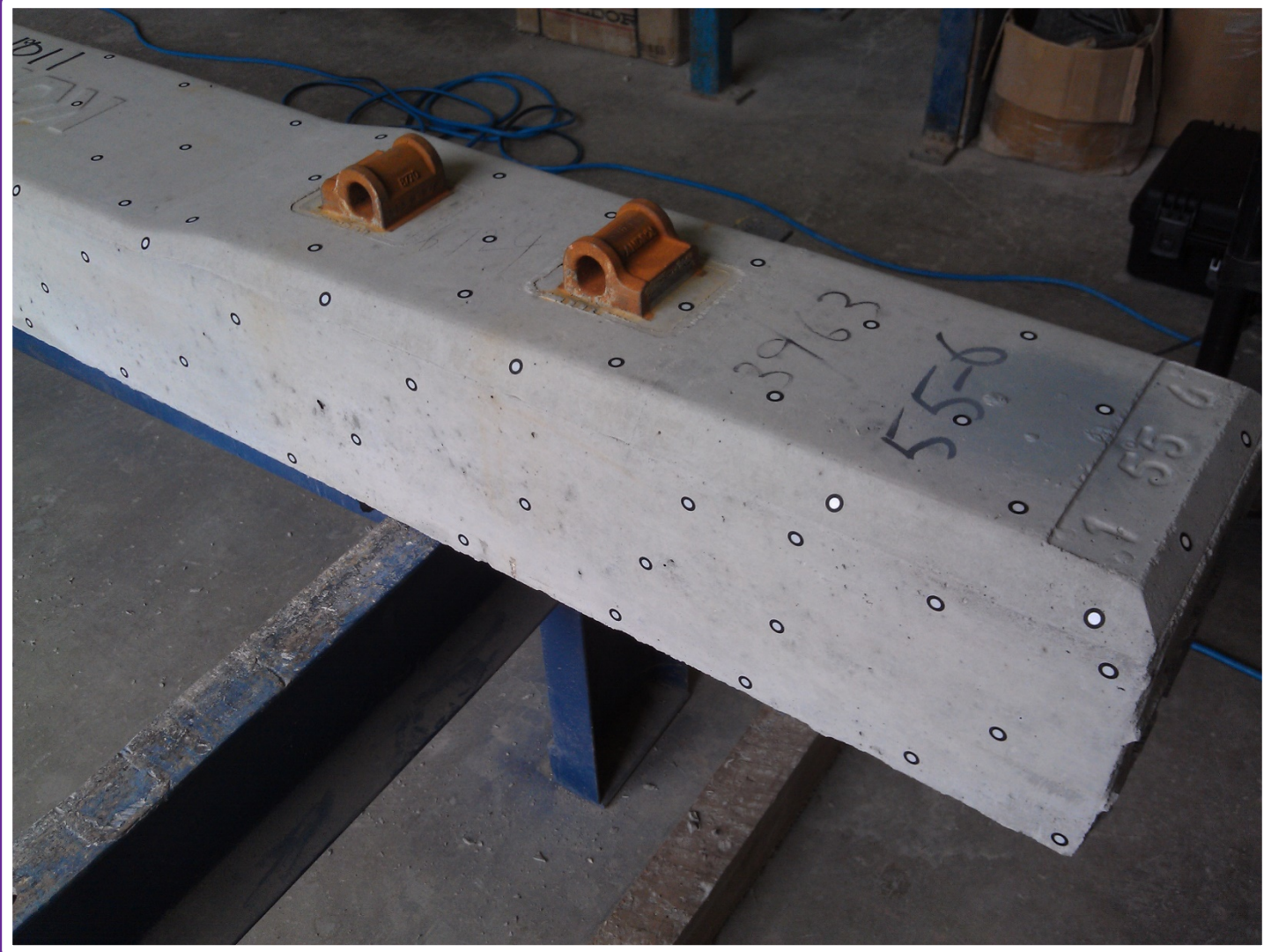


Scallops

CAD (Real Data)

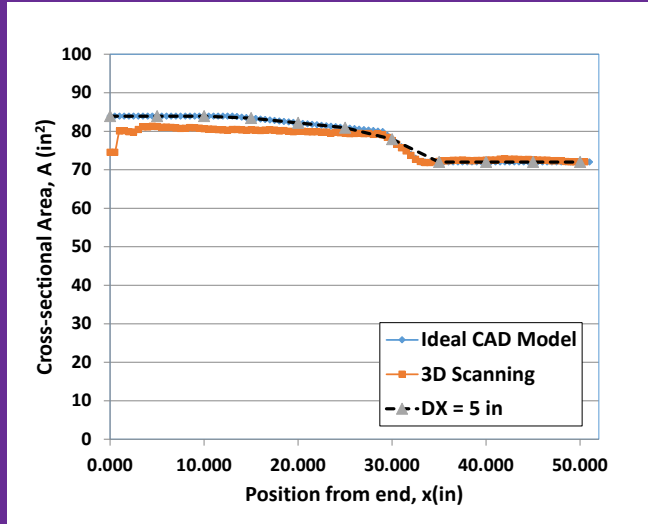
| Δx (in) | L_T (in) |
|-----------------|------------|
| 0.5 | 9.6 |
| 1.0 | 9.6 |
| 2.0 | 9.6 |
| 4.0 | 9.4 |
| 5.0 | 10.0 |
| 6.0 | 9.5 |
| 7.0 | 9.3 |
| 8.0 | 9.9 |

Photographs of Scanned Rocla Tie

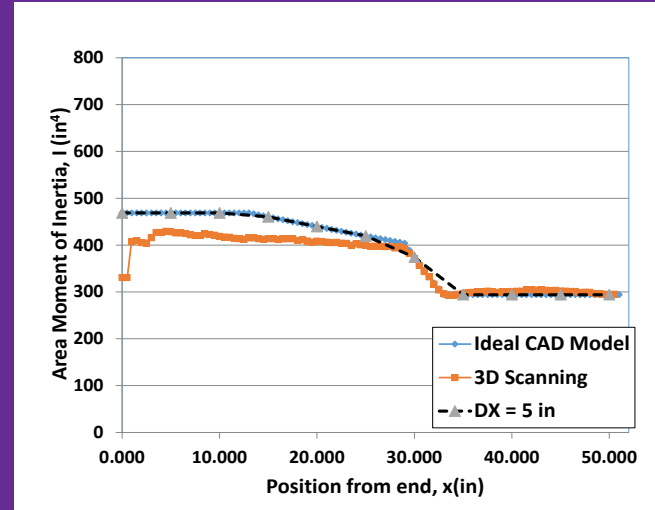


Extracted Rocla Crosstie Cross-Section Parameters

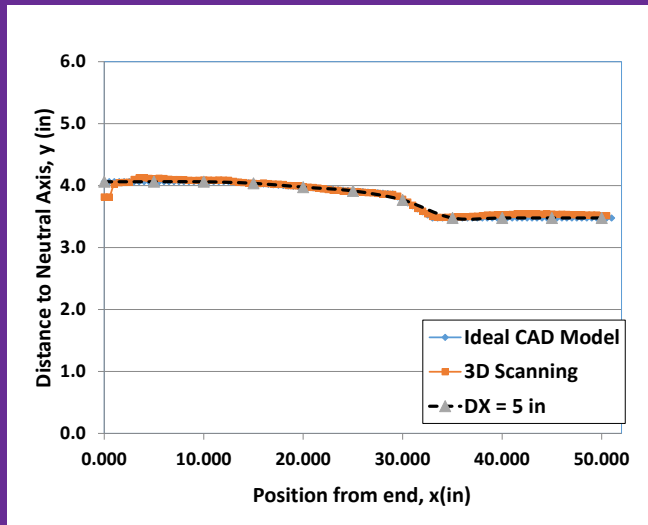
Cross Sectional Area, A



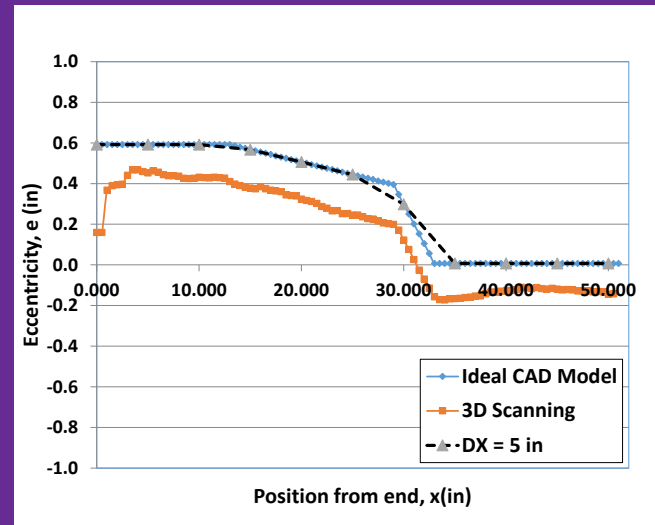
Area Moment of Inertia, I



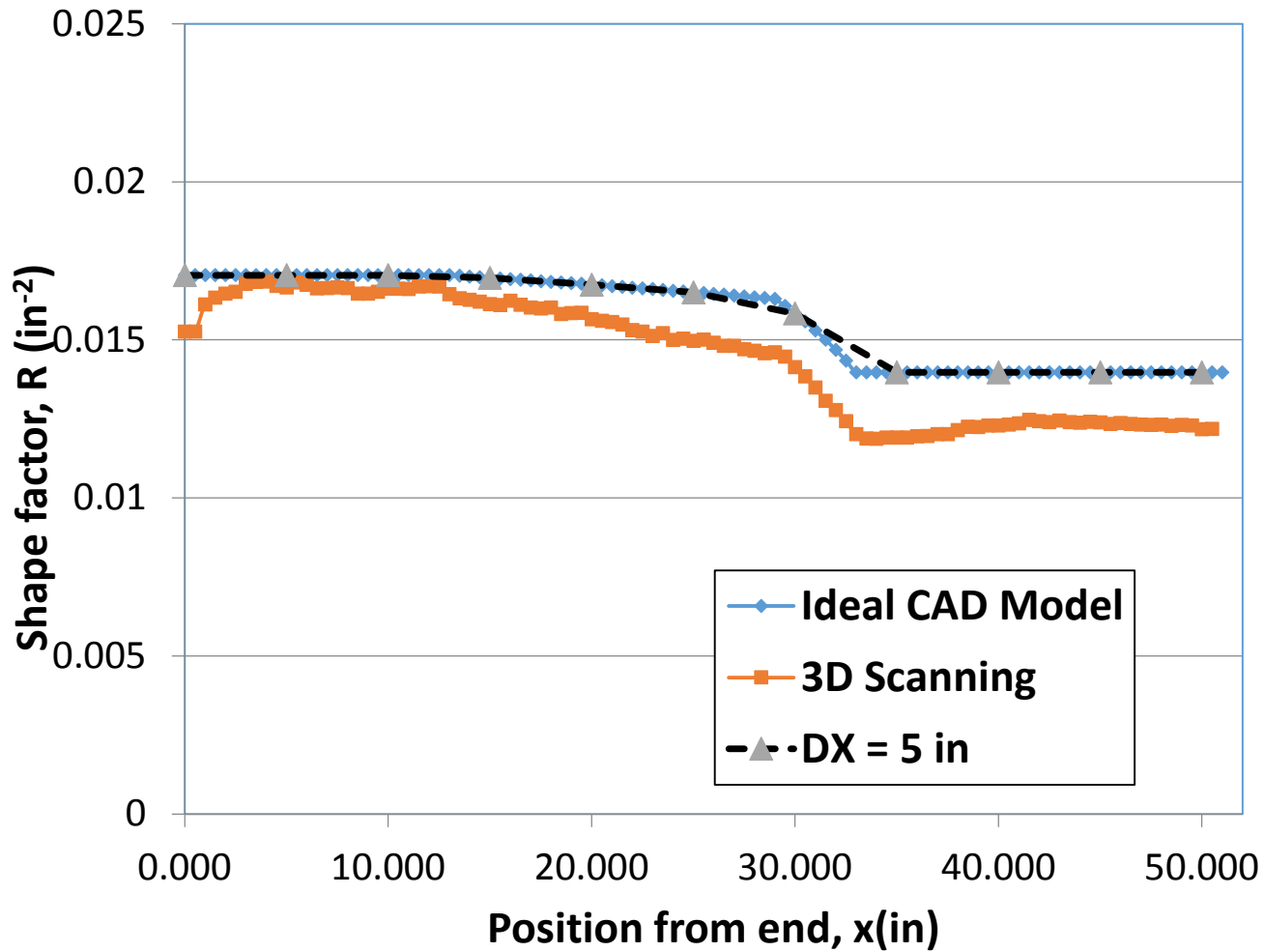
Neutral Axis Position, y



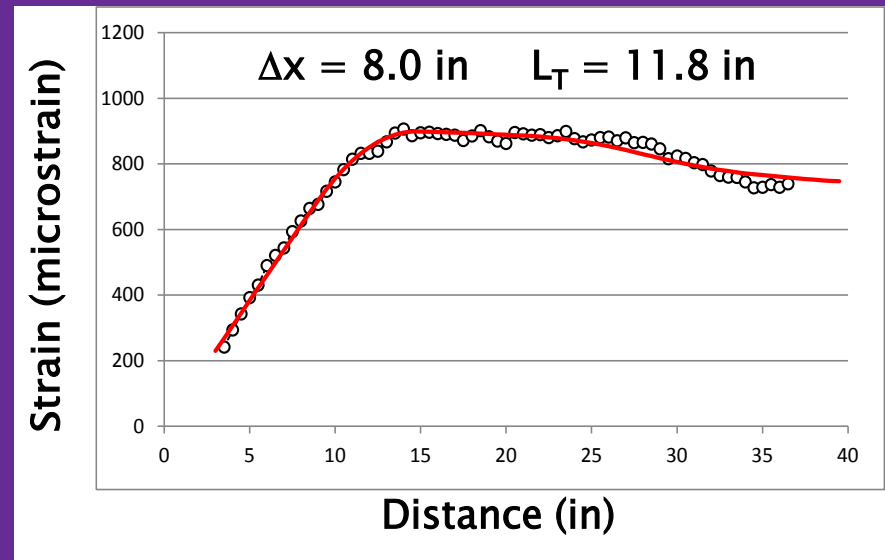
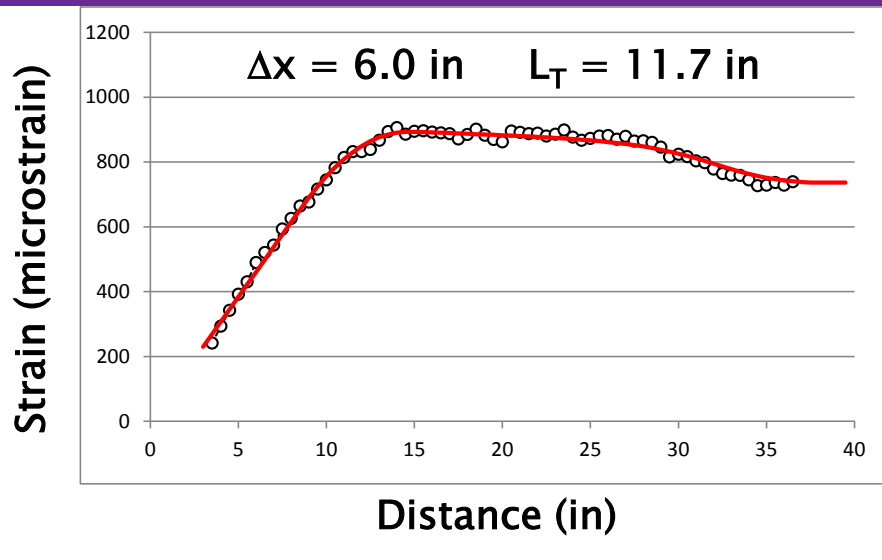
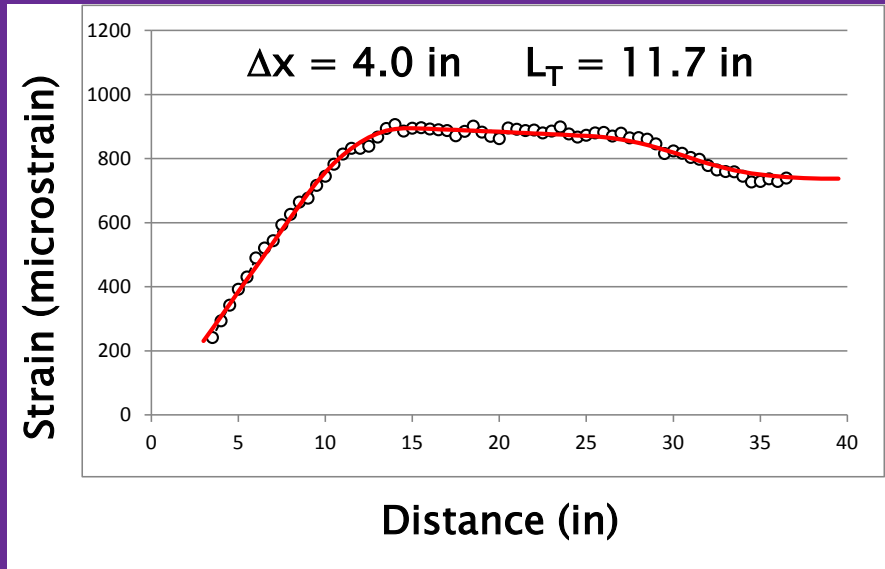
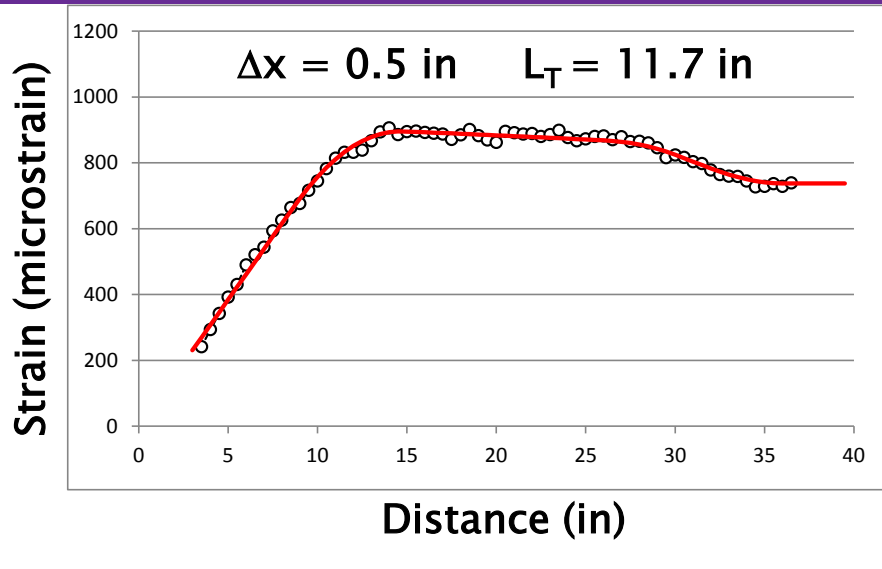
Eccentricity, e



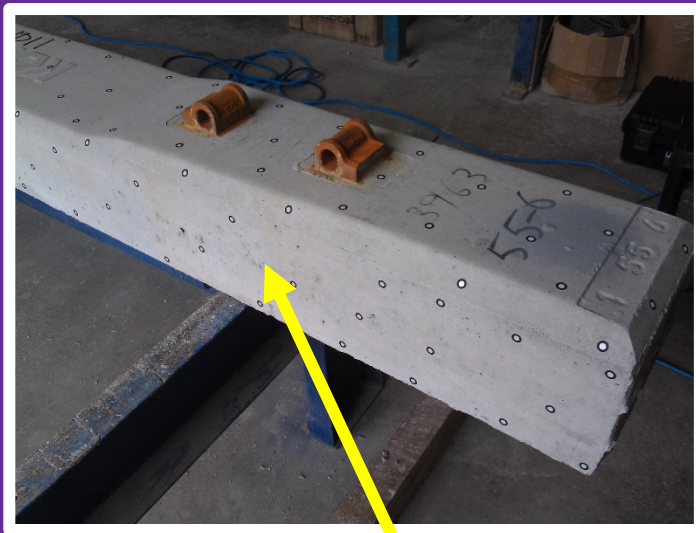
Reduced Resolution Crosstie Shape Factor, R



Effect of Resolution on Strain Profile



Transfer Length Assessment—Effect of Reduced Slicing Resolution (Rocla Tie Results)



Semi-Prismatic Features

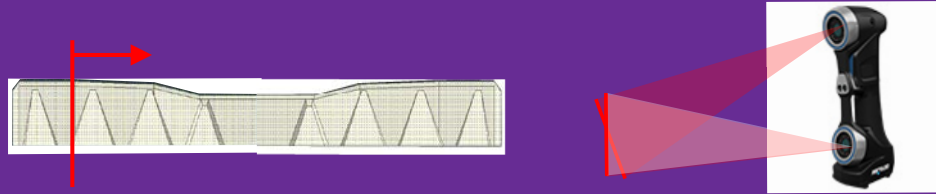
Rocla CAD Tie

| Δx (in) | L_T (in) |
|-----------------|------------|
| 0.5 | 11.7 |
| 1.0 | 11.7 |
| 2.0 | 11.7 |
| 4.0 | 11.7 |
| 5.0 | 11.7 |
| 6.0 | 11.7 |
| 7.0 | 11.7 |
| 8.0 | 11.8 |

Conclusions

- ◆ Detailed 3D Geometrical Cross-Section Parameters Were Extracted (I , y , A , ε) from Crossties.
- ◆ Excellent Agreement with Existing 3D CAD Models
- ◆ Preliminary Results Indicate that Shape Factor Resolution Effect on Transfer Length is Small
- ◆ Gauge Length Smooths Influence of Complex Shape Factor (Scalloping)
- ◆ Coarse Shape Factor Resolution Even Less Sensitive when Complex Scalloping is Absent.

3D Scanning Work in Progress:



- ◆ Systematically Scan Large Sampling of In-Service Ties
- ◆ Extract 3D Geometrical Cross-Section Parameters (I , y , A , e).
- ◆ High-Speed Algorithm for Cross-Section Parameter Assessment is Nearly Complete.
- ◆ Assessment of Parameter Measurement Uncertainty is in Progress.
- ◆ Support Ongoing Testing of In-Service Crossties

Project Sponsors:

Federal Railroad Administration



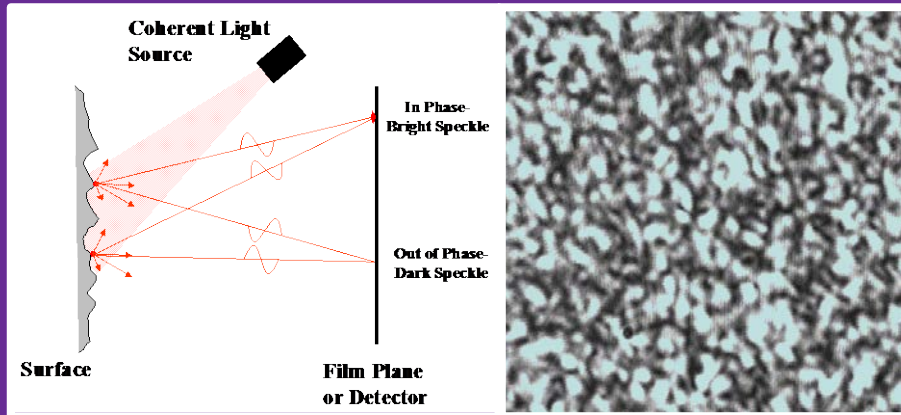
LB Foster
CXT[®] Concrete Ties

KSU Participants:

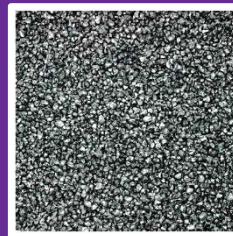


Questions?

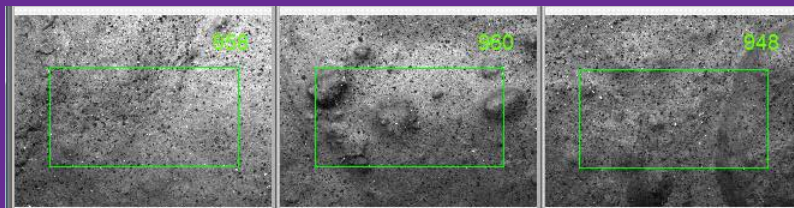
Non-Contact Strain Measurement —Speckle (Feature) Tracking Principle



Laser Speckle
Imaging (LSI)



Painted Reflective
Particle Imaging



Concrete Surface
Roughness Imaging

New Continuous Scanning/Traversing (CST) Strain Measurement System

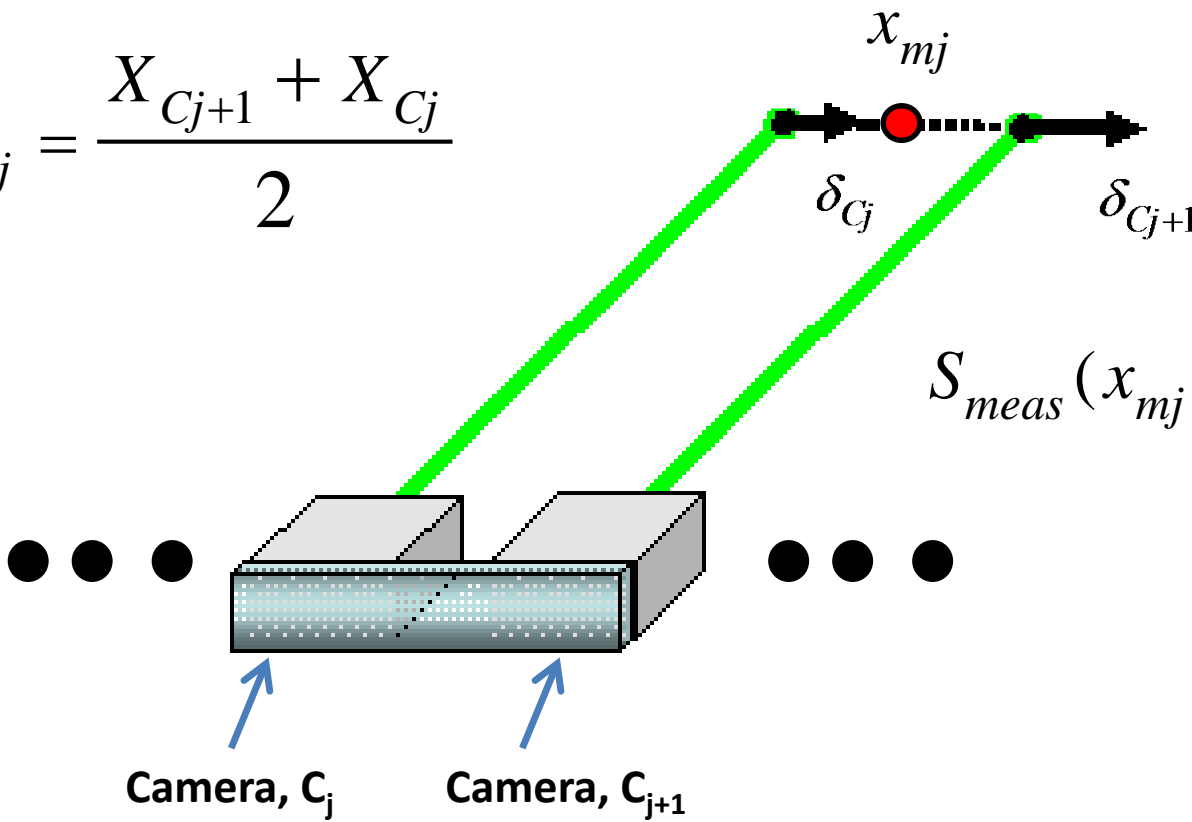


- ◆ Features Improved Depth of Focus
- ◆ “Ring Light” (Strobed) Illumination
- ◆ Jog and Continuous Motion Option (inches/sec)
- ◆ Measurement Resolution (10–20 microstrain)
- ◆ LabVIEW Interface with “Stitching Capability”

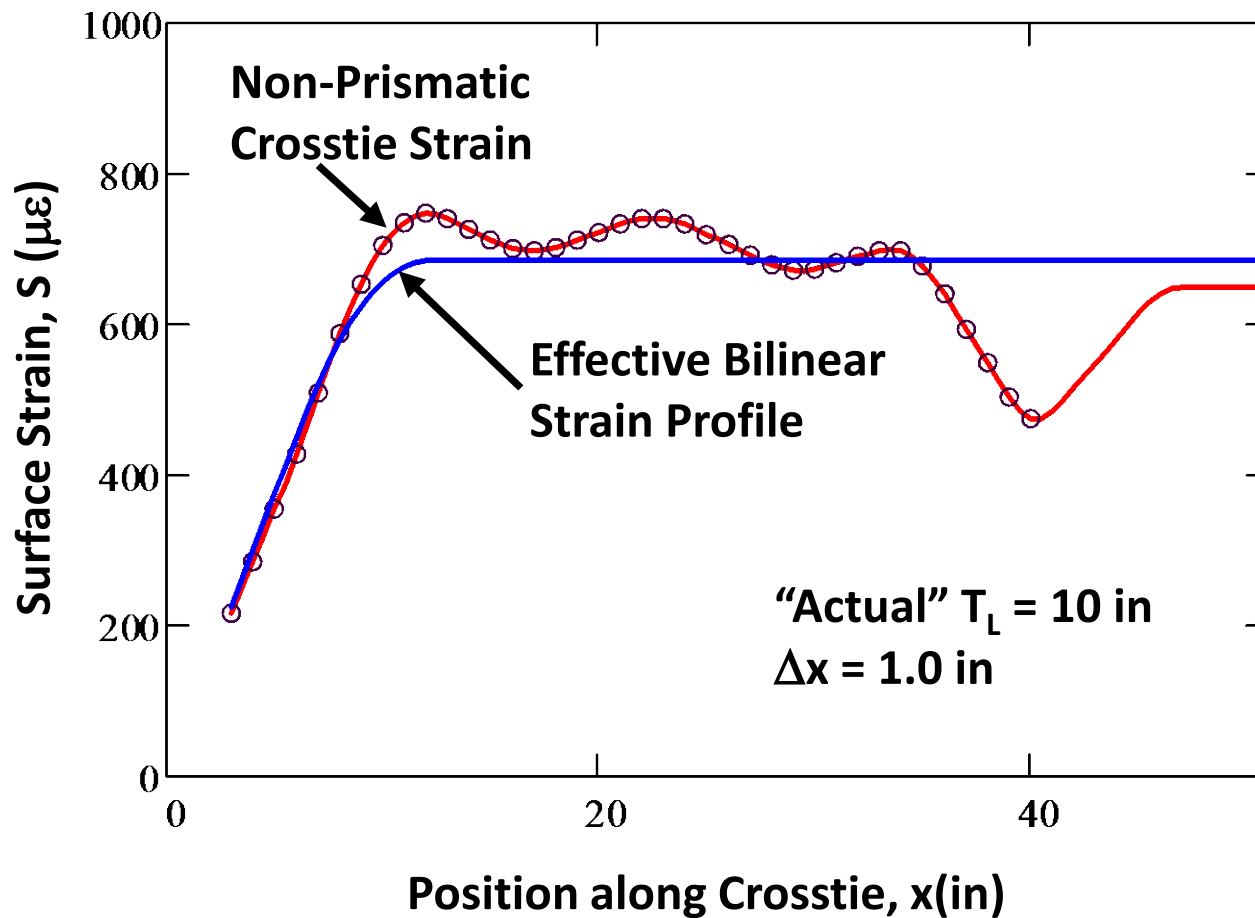
Local Strain from Adjacent Image Displacement Pairs:

$$x_{mj} = \frac{X_{C_{j+1}} + X_{C_j}}{2}$$

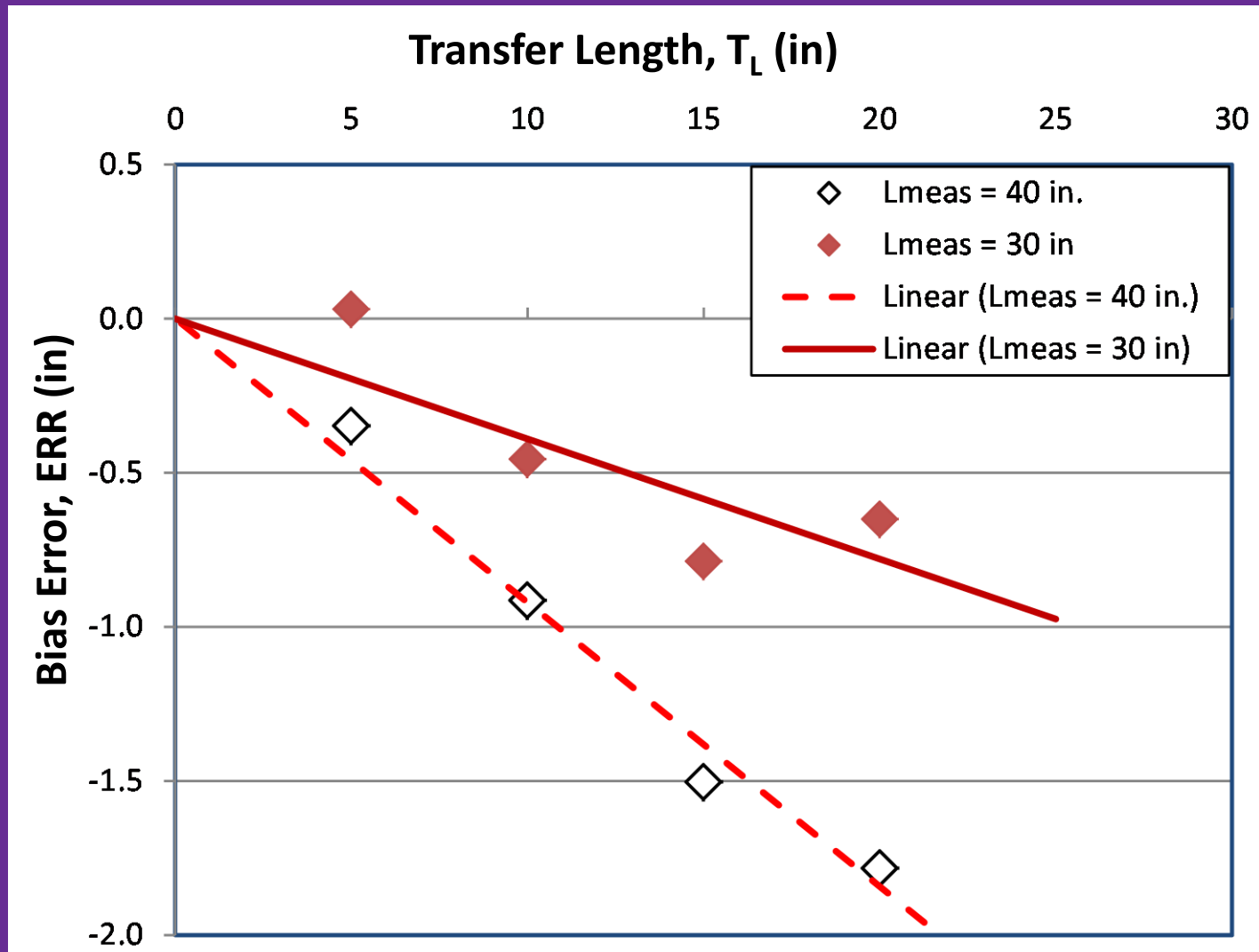
$$S_{meas}(x_{mj}) = \frac{\delta_{C_{j+1}} - \delta_{C_j}}{L_G}$$



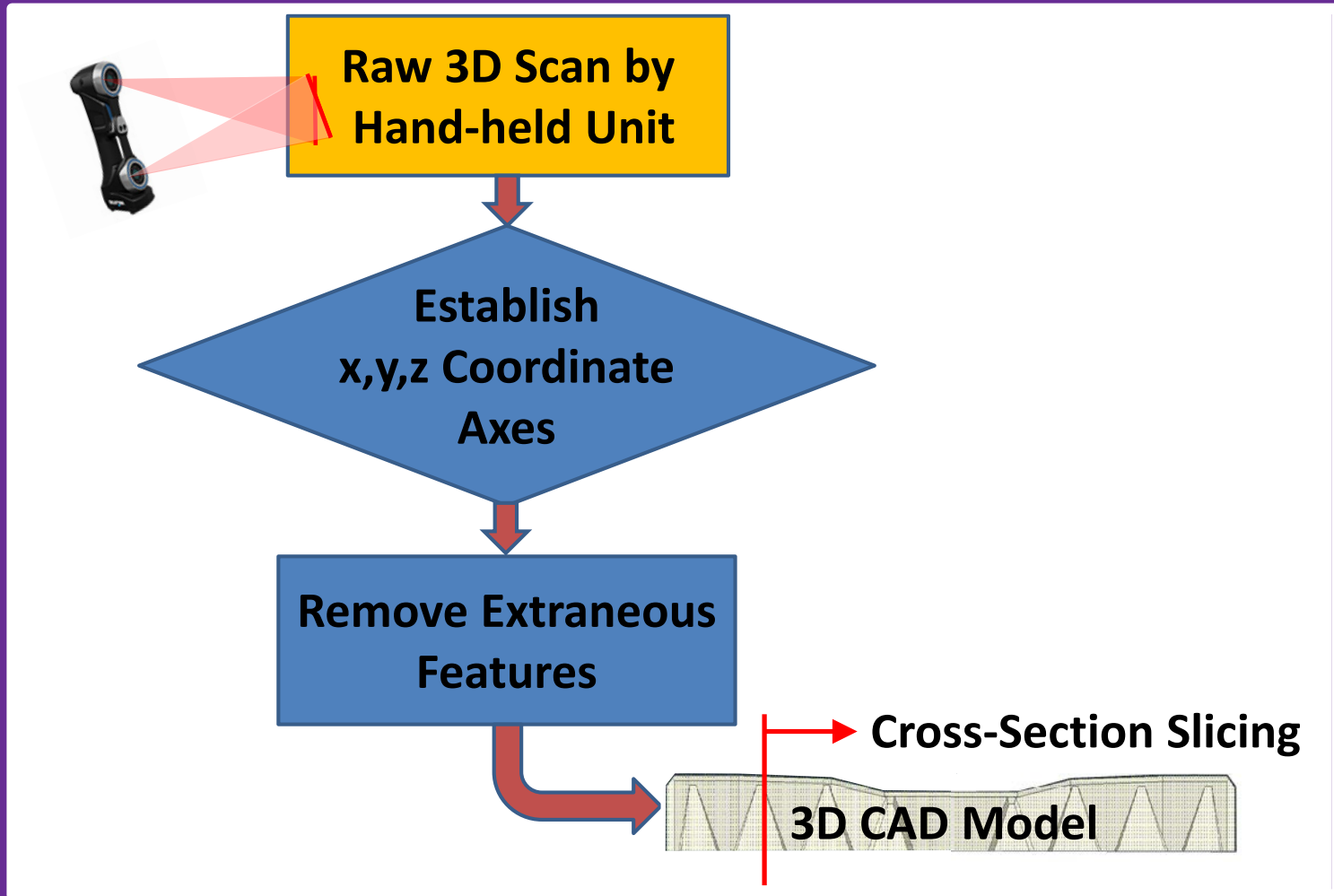
Comparison of **Simulated** Crosstie strain and effective bilinear strain profiles ($L_{\text{meas}} = 40$ in)



Bias in traditional assessment of transfer length based on bilinear surface strain



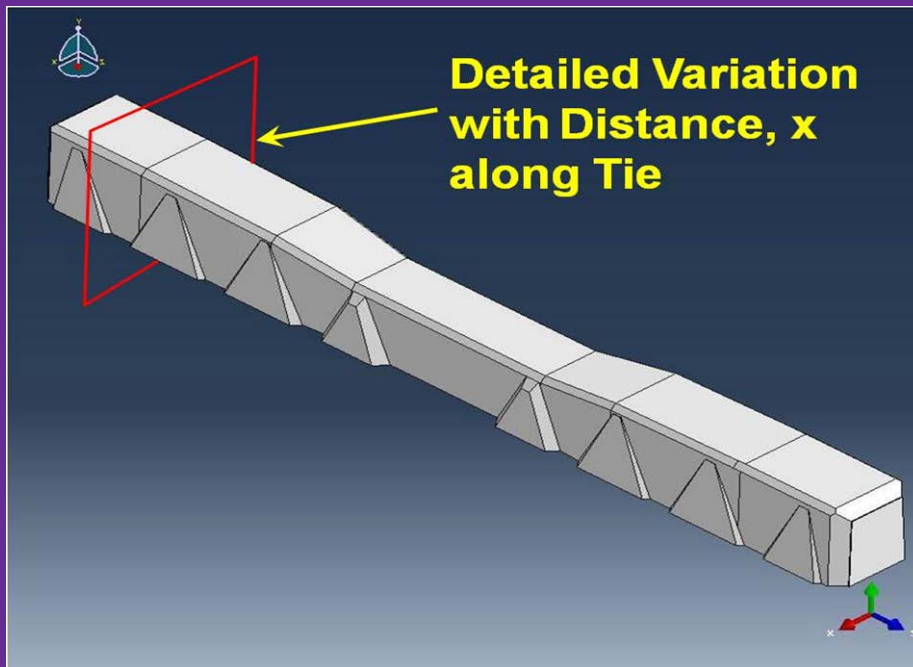
Flow Chart of Crosstie 3D Scan Processing



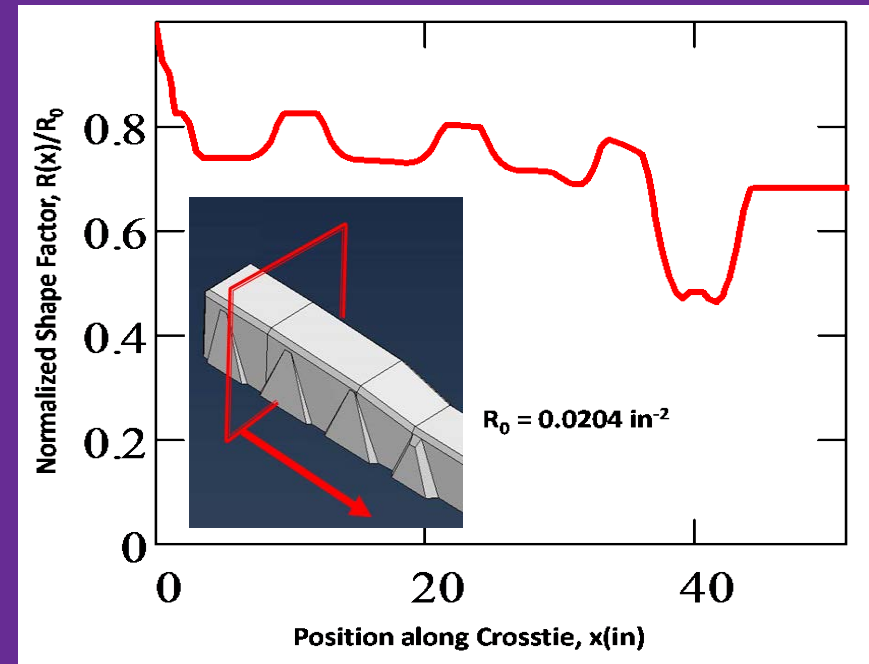
**Current Work is being Conducted
Under FRA Research Project Titled:**

**“Developing Qualification Tests
to Ensure Proper Selection and
Interaction of Pretensioned
Concrete Railroad Tie Materials”**

Geometry of Concrete Railroad Crosstie Yields Complex Shape Factor Variation



3D Shape of Crosstie
(CAD Model or 3D Scan)



Normalized Shape Factor

Traditional 95% AMS Transfer Length

